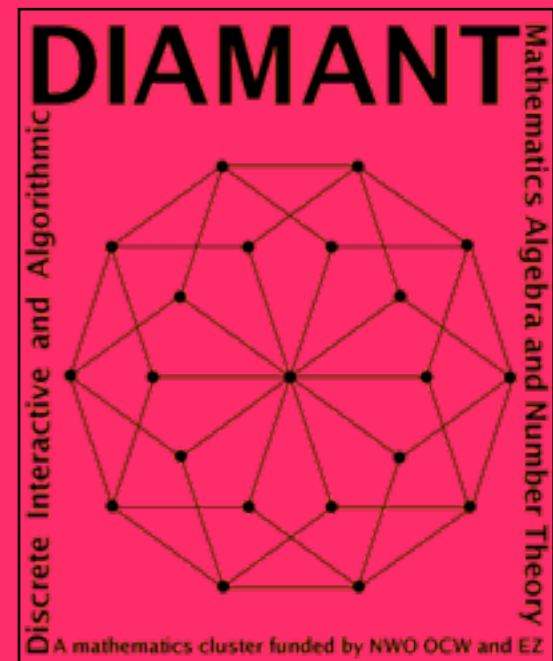


# Construction of Chevalley Bases in all Characteristics

May 29, 2009

Euler Institute for  
**E I D M A**  
Discrete Mathematics and its Applications



Joint work with  
On the occasion of **Arjeh Cohen**'s 60th birthday

**Dan Roozmond**

/ department of mathematics and computer science

**TU** / **e**

Technische Universiteit  
**Eindhoven**  
University of Technology

- ▶ **What is a Lie algebra?**
- ▶ **What is a Chevalley basis?**
- ▶ **How to compute Chevalley bases?**
- ▶ **What next?**

# What is a Lie Algebra?

- ▶ **Vector space:**  $\mathbb{F}^n$



# What is a Lie Algebra?

- ▶ **Vector space:**  $\mathbb{F}^n$
- ▶ **Multiplication**  $[\cdot, \cdot] : L \times L \mapsto L$  that is
  - **Bilinear,**
  - **Anti-symmetric,**
  - **Satisfies Jacobi identity:**

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

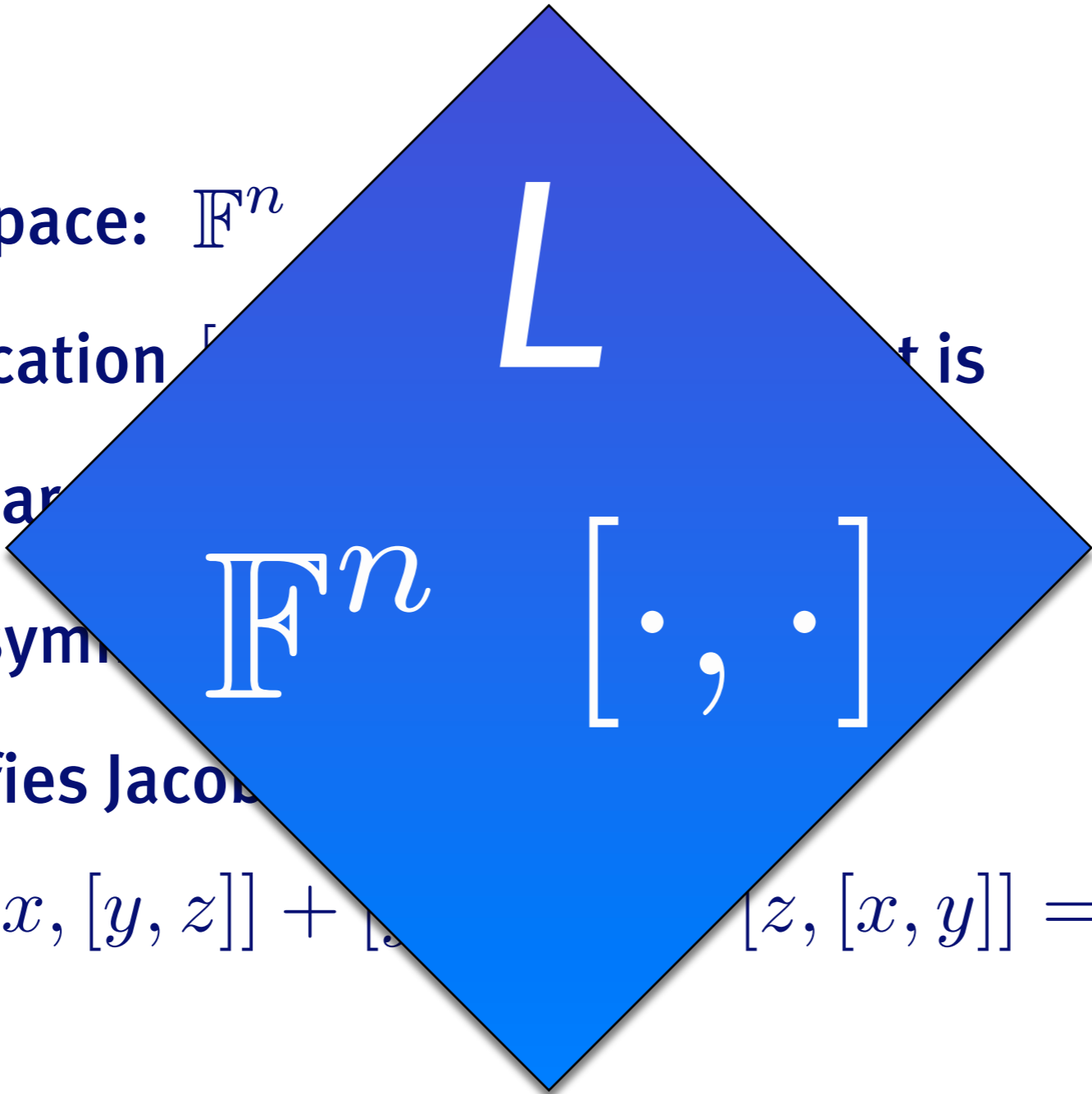


# What is a Lie Algebra?

- ▶ **Vector space:**  $\mathbb{F}^n$
- ▶ **Multiplication**  $[\cdot, \cdot]$  is

- **Bilinear**
- **Anti-symmetric**
- **Satisfies Jacobi**

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$



## Classification (Killing, Cartan)

If  $\text{char}(\mathbb{F}) = 0$  and  $\mathbb{F}$  algebraically closed, then the only simple Lie algebras are:

$$A_n \ (n \geq 1) \qquad E_6, E_7, E_8$$

$$B_n \ (n \geq 2) \qquad F_4$$

$$C_n \ (n \geq 3) \qquad G_2$$

$$D_n \ (n \geq 4)$$



# Why Study Lie Algebras?

5 of 29

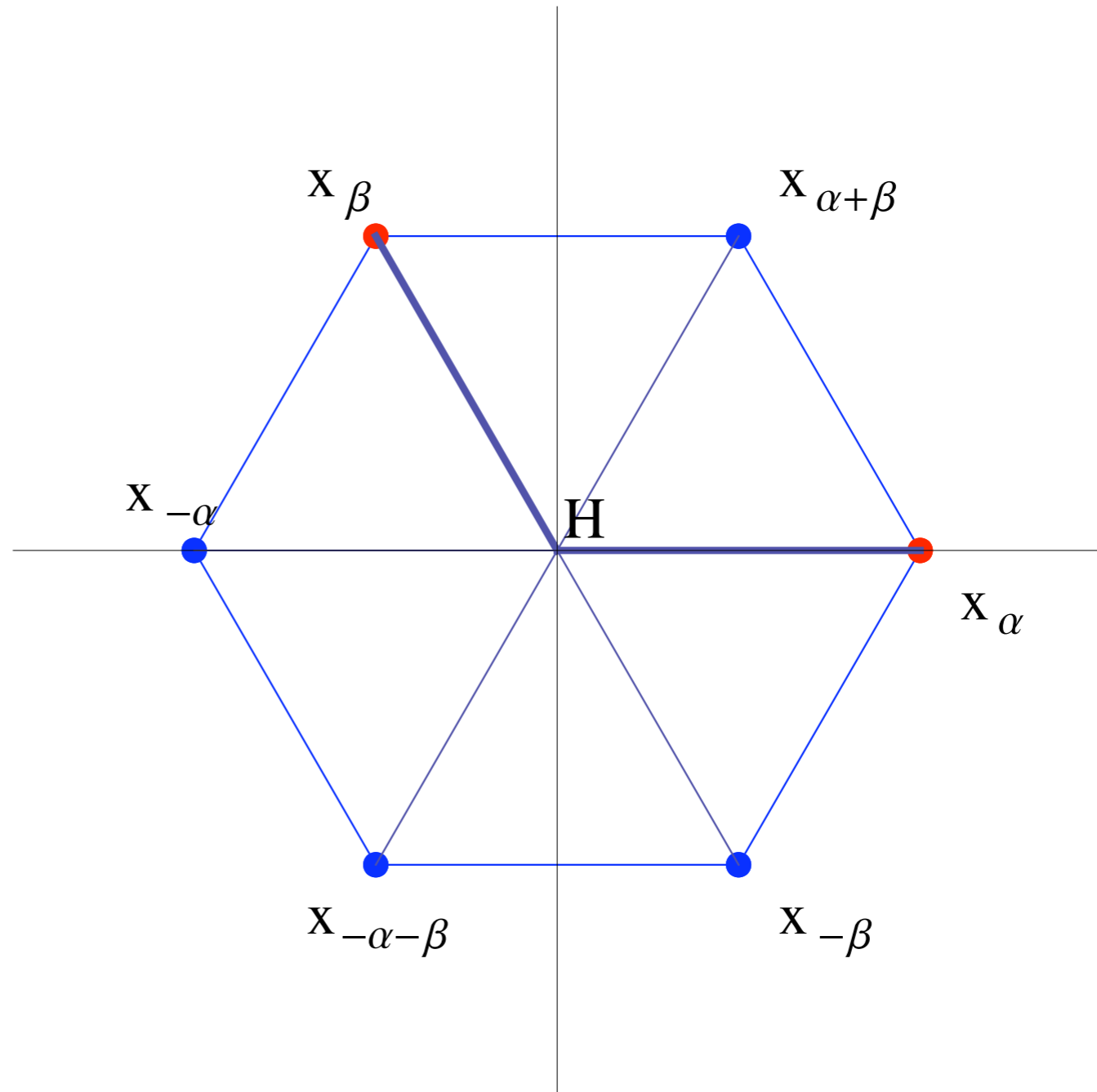
/ department of mathematics and computer science

- ▶ **Study *groups* by their Lie algebras:**
  - Simple algebraic group  $G \leftrightarrow$  Unique Lie algebra  $L$
  - Many properties carry over to  $L$
  - Easier to calculate in  $L$
  - $G \leq \text{Aut}(L)$ , often even  $G = \text{Aut}(L)$



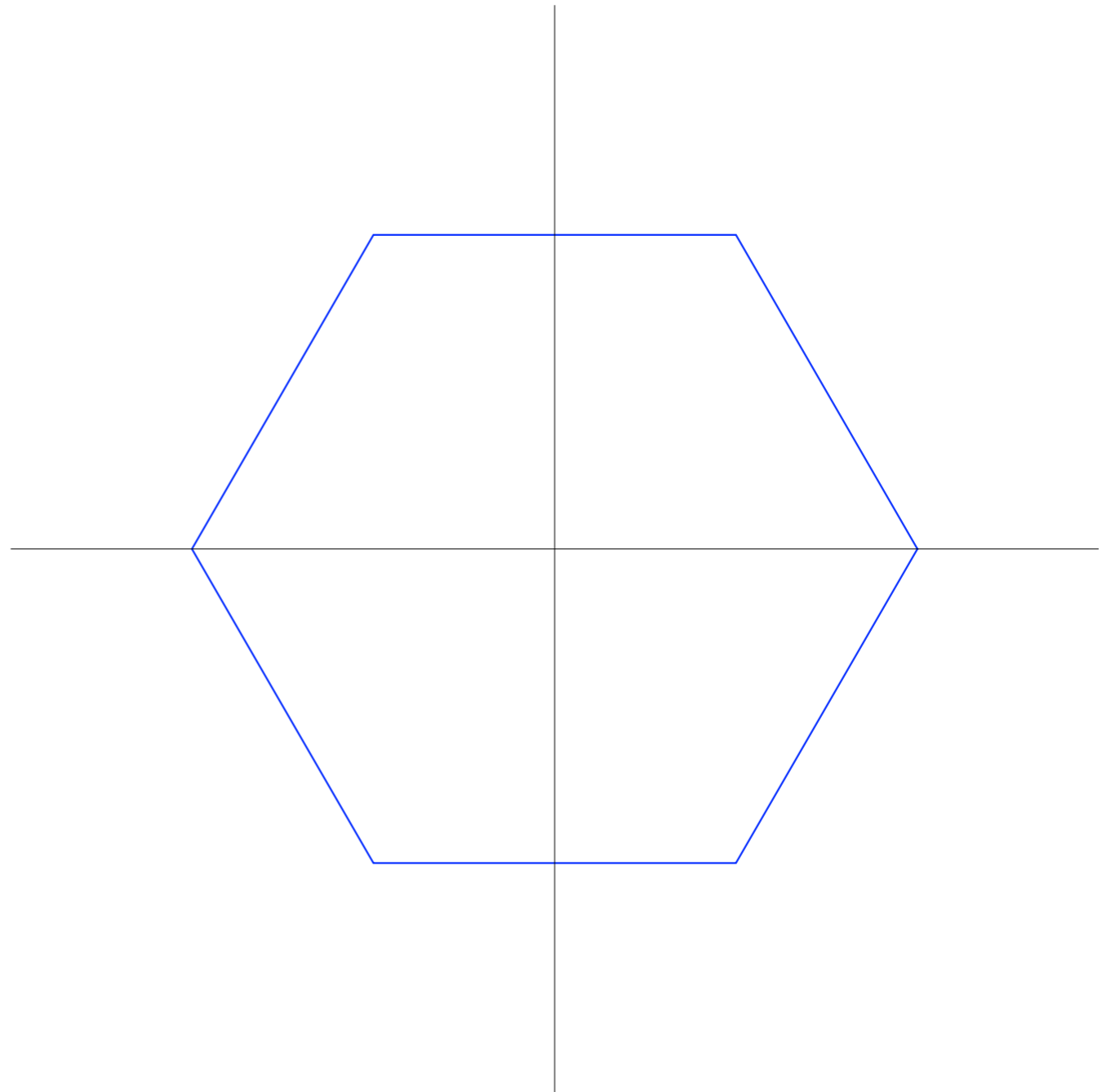
- ▶ **Study *groups* by their Lie algebras:**
  - Simple algebraic group  $G \leftrightarrow$  Unique Lie algebra  $L$
  - Many properties carry over to  $L$
  - Easier to calculate in  $L$
  - $G \leq \text{Aut}(L)$ , often even  $G = \text{Aut}(L)$
- ▶ **Opportunities for:**
  - Recognition
  - Conjugation
  - ...

- ▶ **Study *groups* by their Lie algebras:**
  - Simple algebraic group  $G \leftrightarrow$  Unique Lie algebra  $L$
  - Many properties carry over to  $L$
  - Easier to calculate in  $L$
  - $G \leq \text{Aut}(L)$ , often even  $G = \text{Aut}(L)$
- ▶ **Opportunities for:**
  - Recognition
  - Conjugation
  - ...
- ▶ **Because there are problems to be solved!**
  - ... and a thesis to be written...

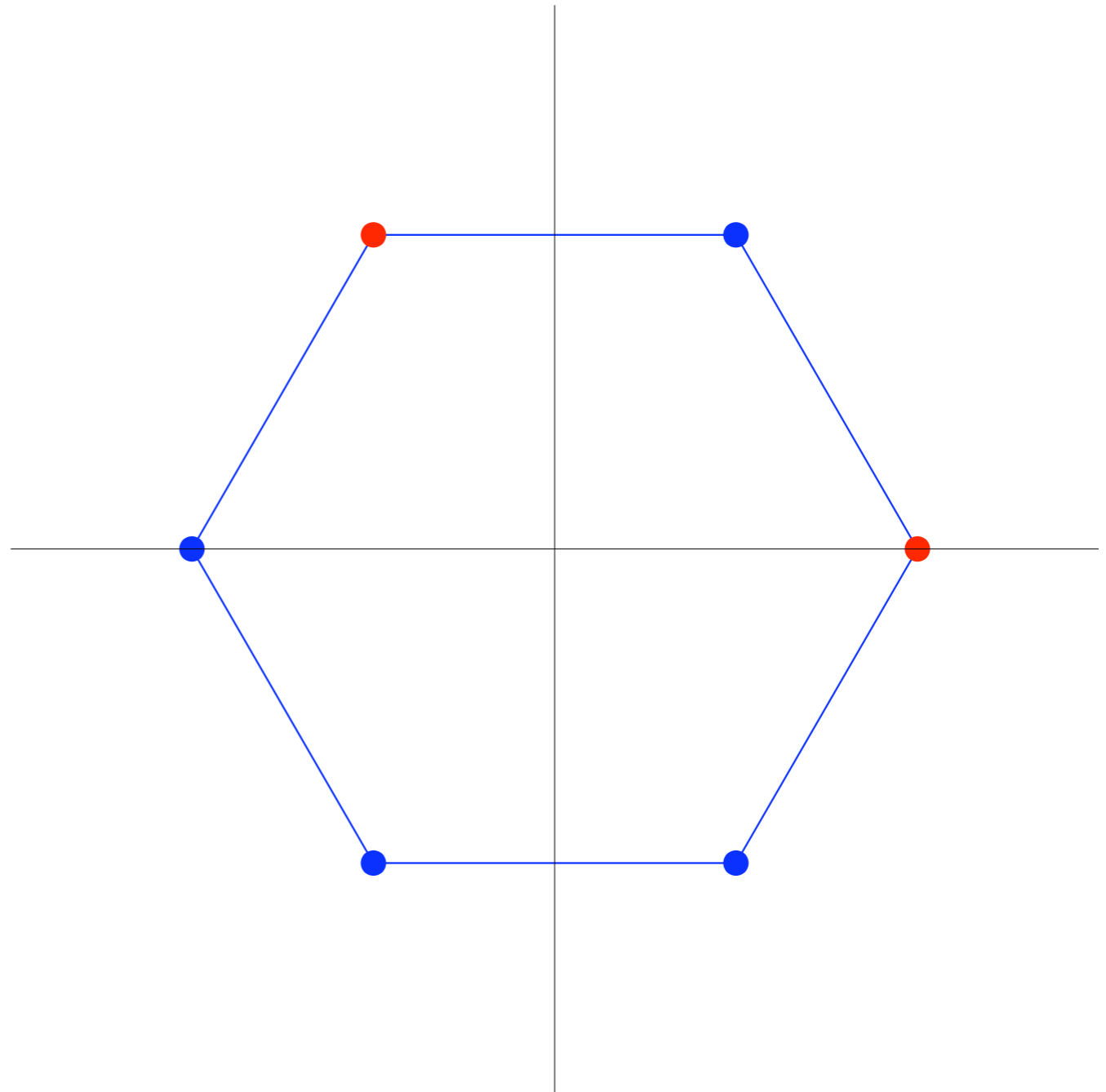


Many Lie algebras have a *Chevalley basis*!

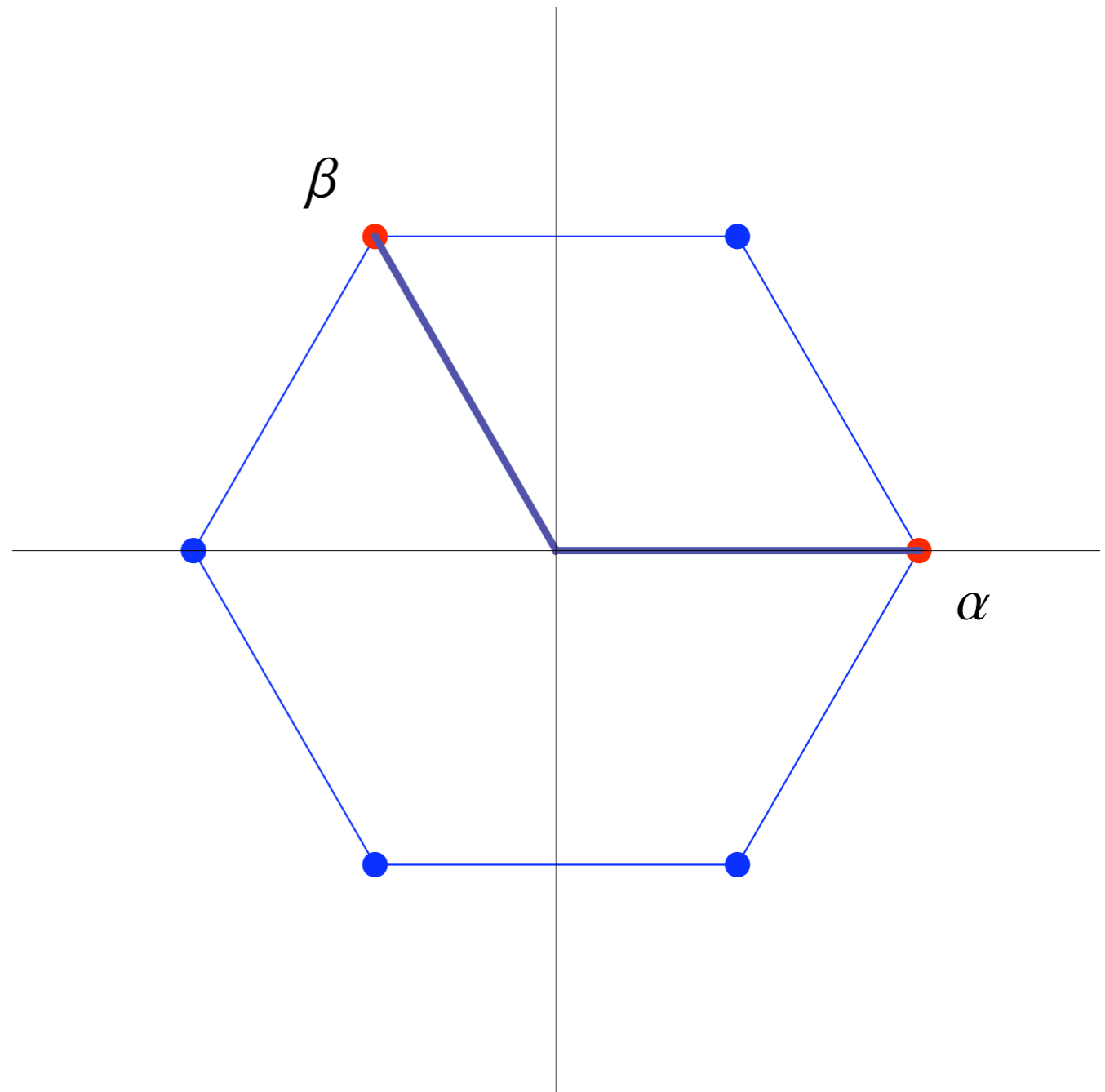
▶ **A hexagon**



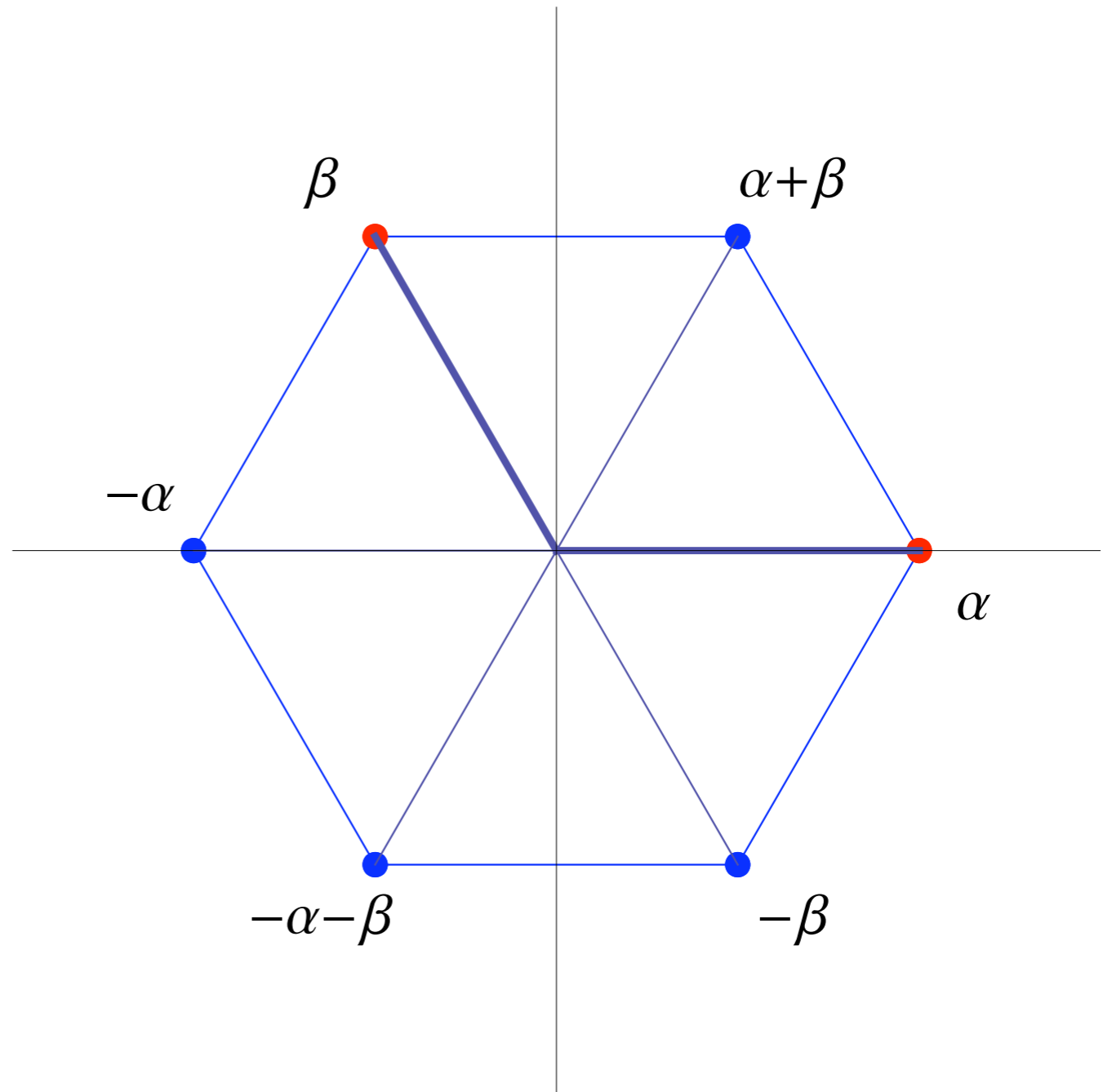
▶ A hexagon



- ▶ A hexagon



- ▶ A hexagon
- ▶ A root system of type  $A_2$



## Definition (Root Datum)

$$R = (X, \Phi, Y, \Phi^\vee), \quad \langle \cdot, \cdot \rangle : X \times Y \rightarrow \mathbb{Z}$$



## Definition (Root Datum)

$$R = (X, \Phi, Y, \Phi^\vee), \quad \langle \cdot, \cdot \rangle : X \times Y \rightarrow \mathbb{Z}$$

- ▶  $X, Y$ : dual free  $\mathbb{Z}$ -modules,
- ▶ put in duality by  $\langle \cdot, \cdot \rangle$ ,
- ▶  $\underline{\Phi} \subseteq X$ : roots,
- ▶  $\underline{\Phi}^\vee \subseteq Y$ : coroots.

## Definition (Root Datum)

$$R = (X, \Phi, Y, \Phi^\vee), \quad \langle \cdot, \cdot \rangle : X \times Y \rightarrow \mathbb{Z}$$

- ▶  $X, Y$ : dual free  $\mathbb{Z}$ -modules,
- ▶ put in duality by  $\langle \cdot, \cdot \rangle$ ,
- ▶  $\Phi \subseteq X$ : roots,
- ▶  $\Phi^\vee \subseteq Y$ : coroots.

*One Root System*  $\longrightarrow$   $\left\{ \begin{array}{l} \textit{Several Root Data:} \\ \text{“adjoint”} \\ \vdots \\ \text{“simply connected”} \end{array} \right.$

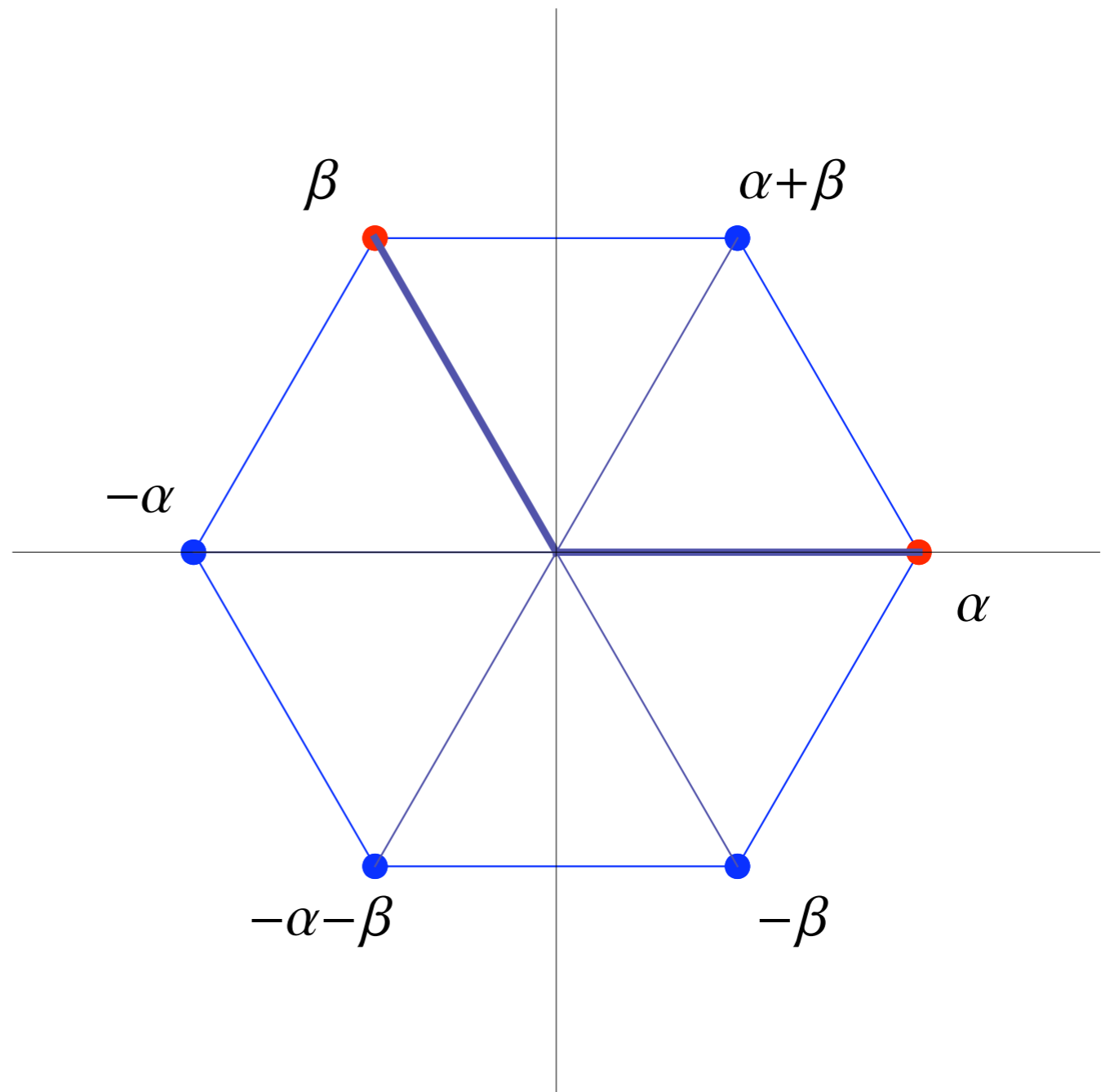
## Definition (Root Datum)

$$R = (X, \Phi, Y, \Phi^\vee), \quad \langle \cdot, \cdot \rangle : X \times Y \rightarrow \mathbb{Z}$$

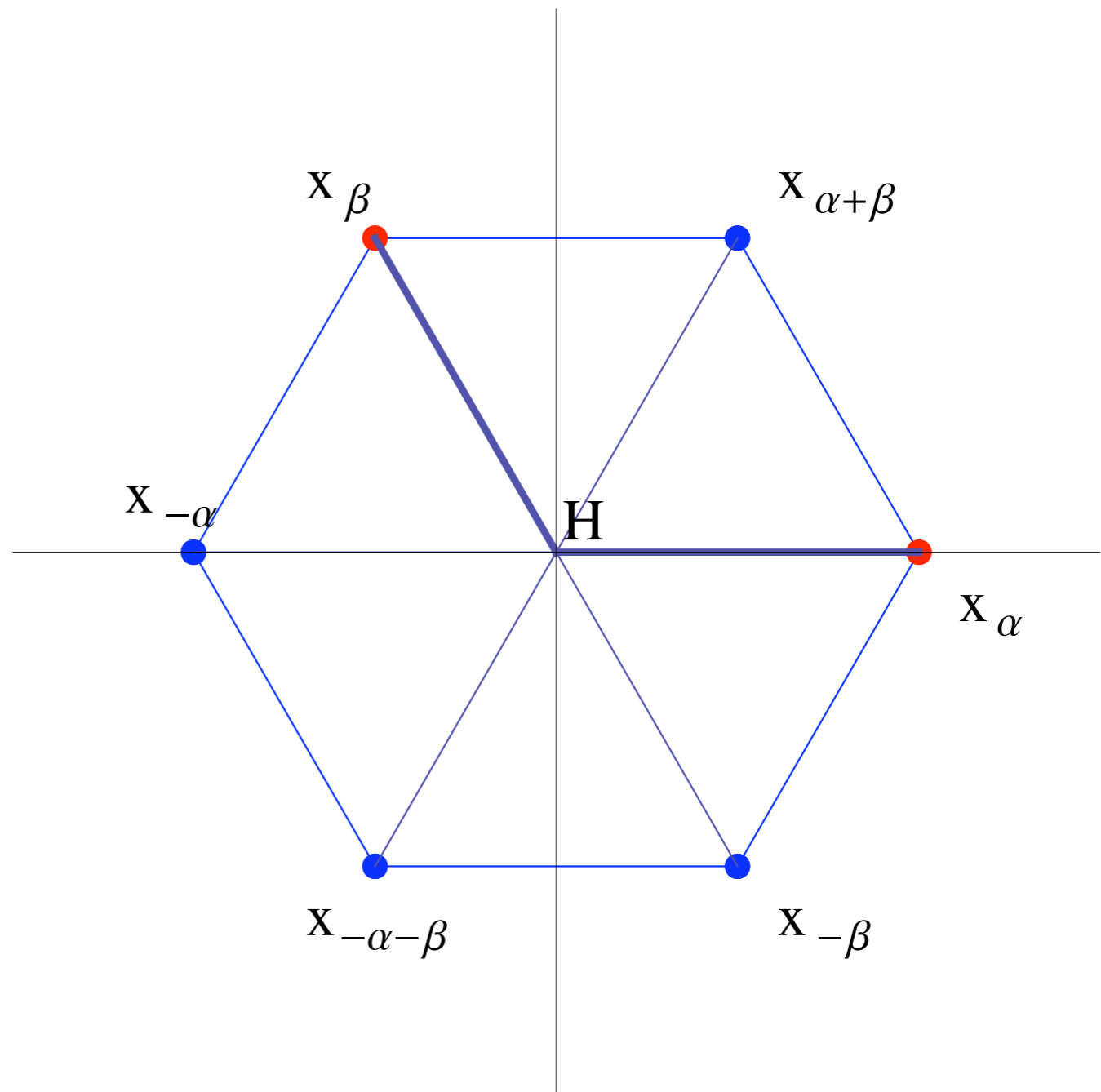
*One Root System*  $\longrightarrow$   $\left\{ \begin{array}{l} \textit{Several Root Data:} \\ \text{“adjoint”} \\ \vdots \\ \text{“simply connected”} \end{array} \right.$

**Irreducible Root Data:**  $A_n, B_n, C_n, D_n, E_6, E_7, E_8, F_4, G_2.$

- ▶ A hexagon
- ▶ A root system of type  $A_2$



- ▶ A hexagon
- ▶ A root system of type  $A_2$
- ▶ A Lie algebra of type  $A_2$



## Definition (Chevalley Basis)

**Formal basis:**  $L = \bigoplus_{i=1, \dots, n} \mathbb{F}h_i \oplus \bigoplus_{\alpha \in \Phi} \mathbb{F}x_\alpha$

**Bilinear anti-symmetric multiplication satisfies** ( $i, j \in \{1, \dots, n\}; \alpha, \beta \in \Phi$ ):

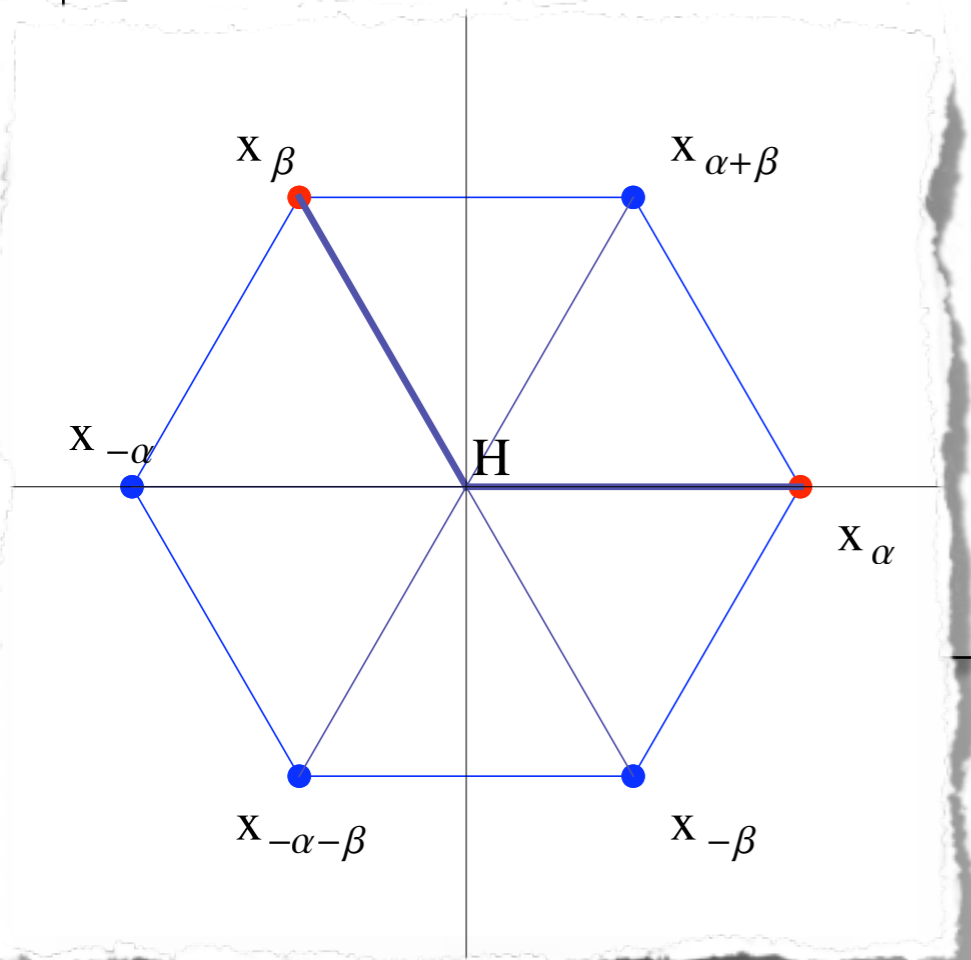
$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

## Definition (Chevalley Basis)

**Formal basis:** 
$$L = \bigoplus_{i=1, \dots, n} \mathbb{F}h_i \oplus \bigoplus_{\alpha \in \Phi} \mathbb{F}x_\alpha$$

**Bilinear anti-symmetric multiplication satisfies** ( $i, j \in \{1, \dots, n\}; \alpha, \beta \in \Phi$ ):



$$\begin{aligned}
 [h_i, h_j] &= 0, \\
 [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\
 [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\
 [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases}
 \end{aligned}$$

and the Jacobi identity.

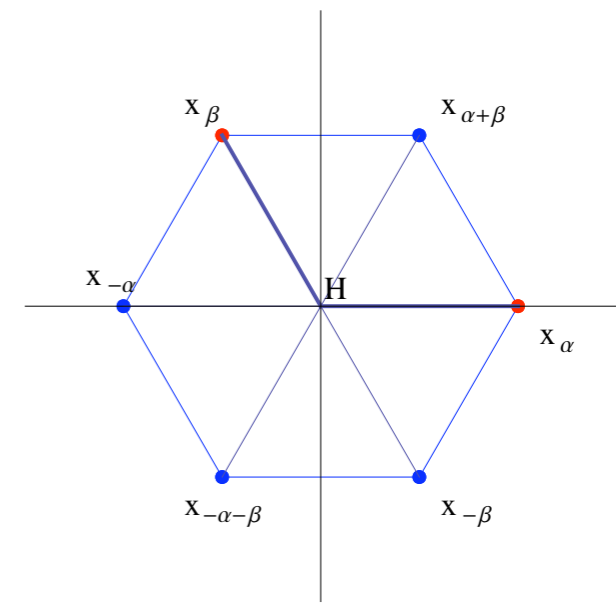
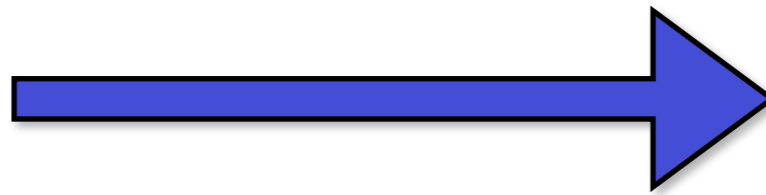
## Why Chevalley bases?

- ▶ Because transformation between two Chevalley bases is an automorphism of  $L$ ,
- ▶ So we can test isomorphism between two Lie algebras (and find isomorphisms!) by computing Chevalley bases.

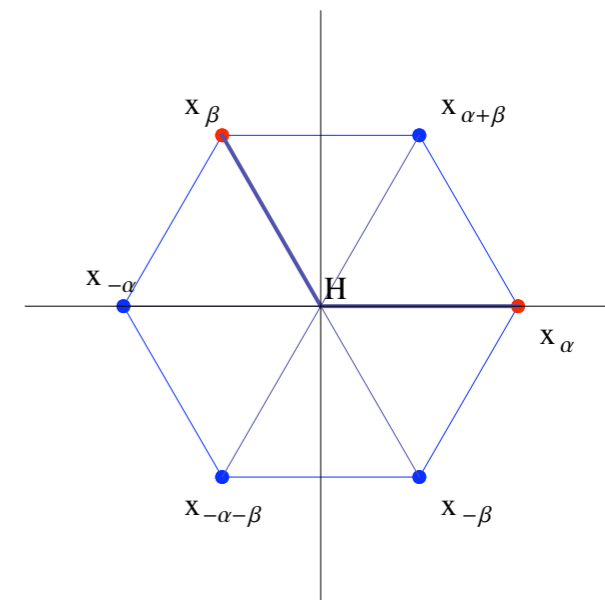
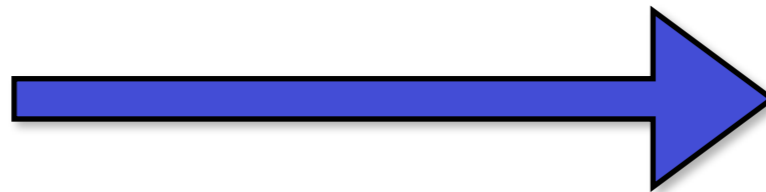


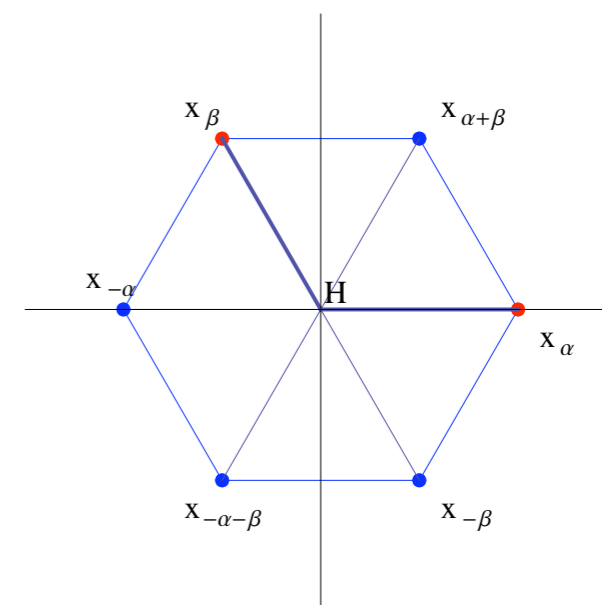
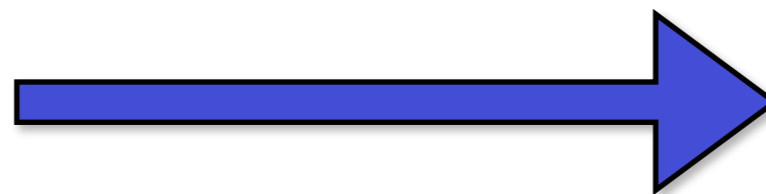
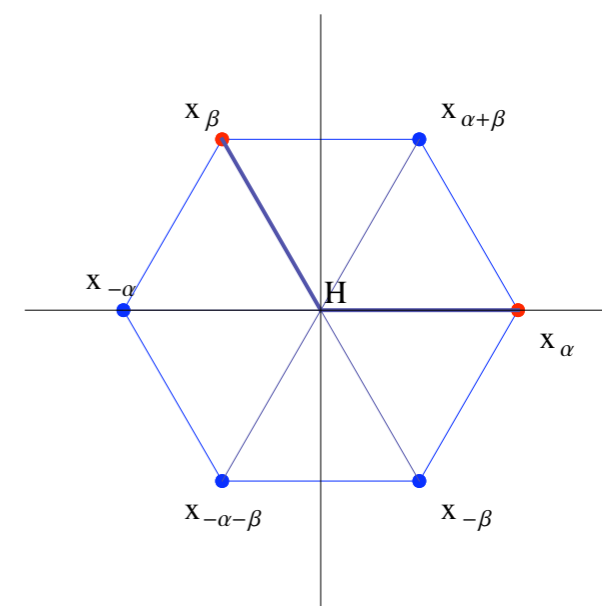
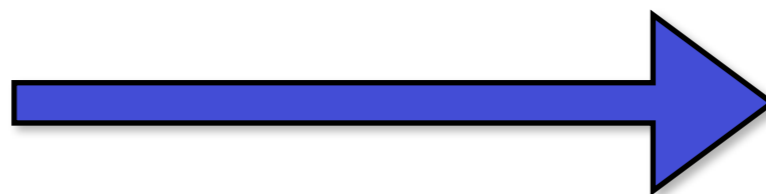
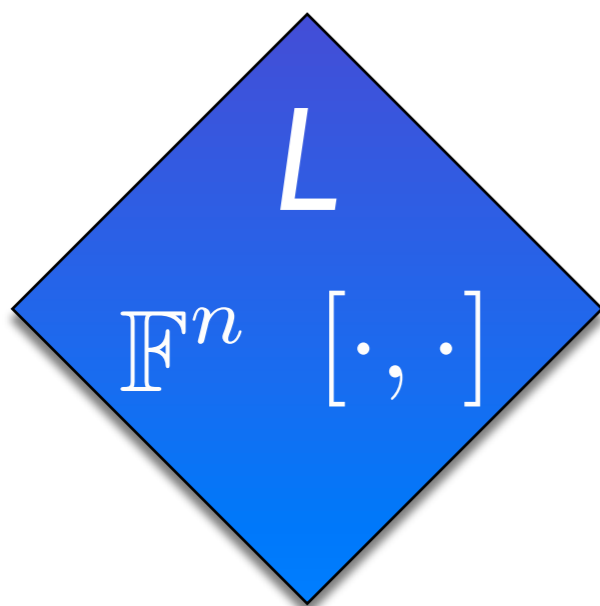


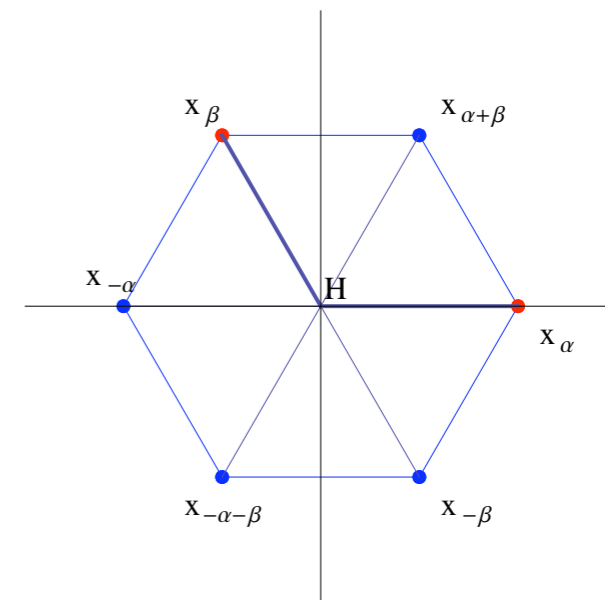
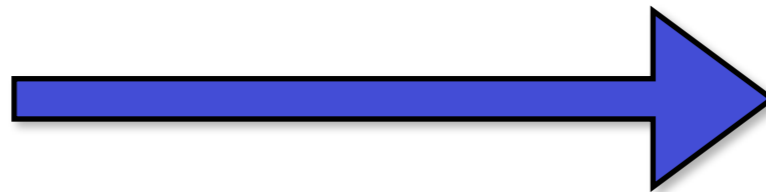
# Why?



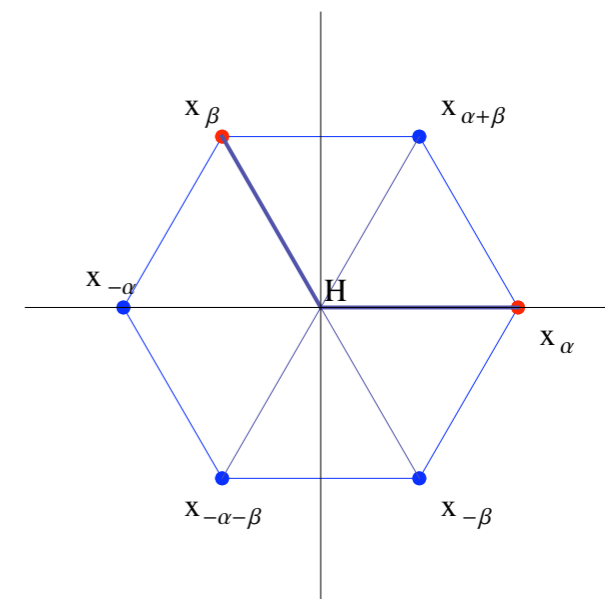
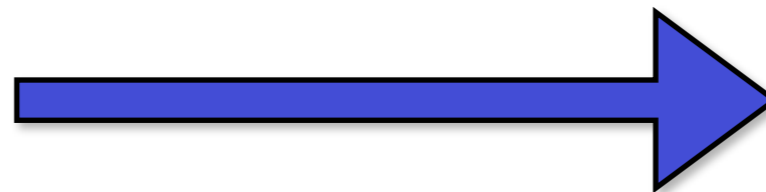
# Why?

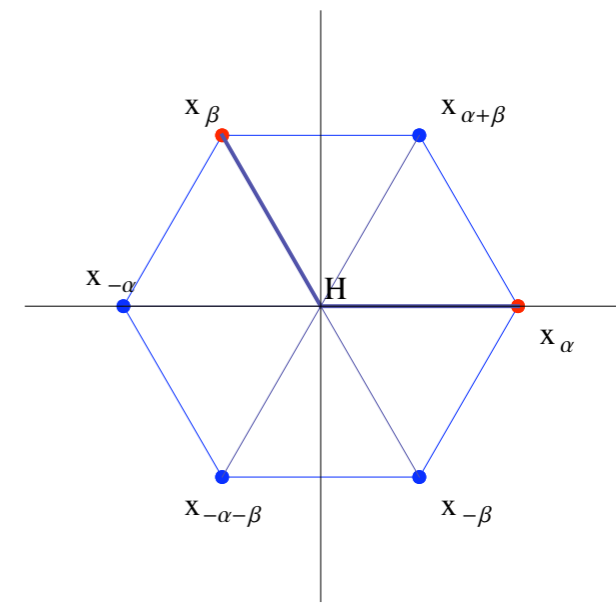
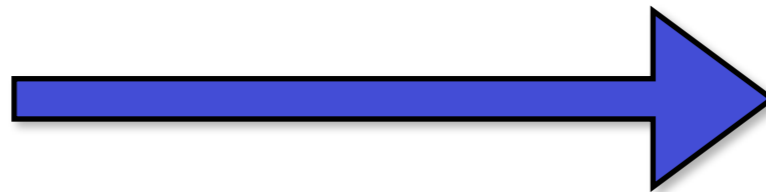




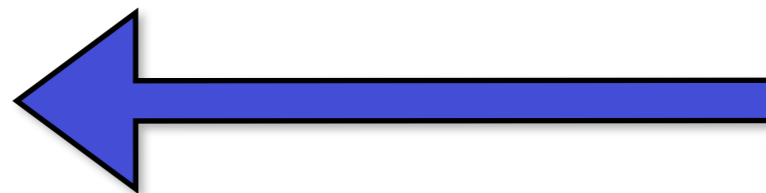


equal

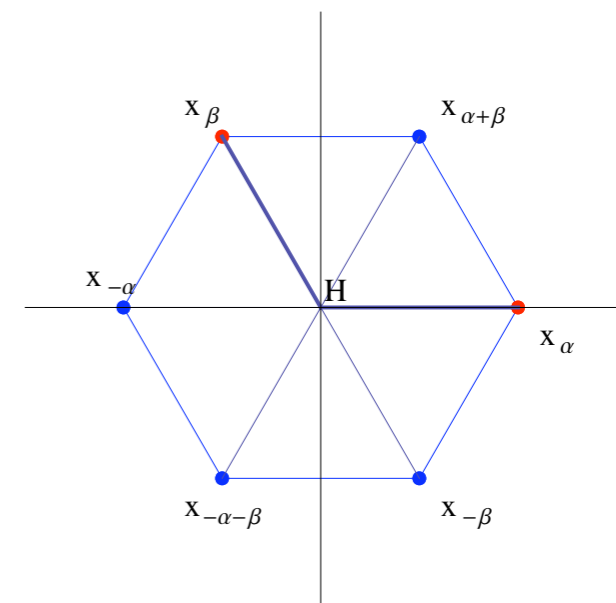
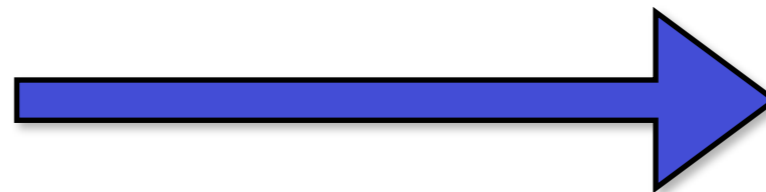




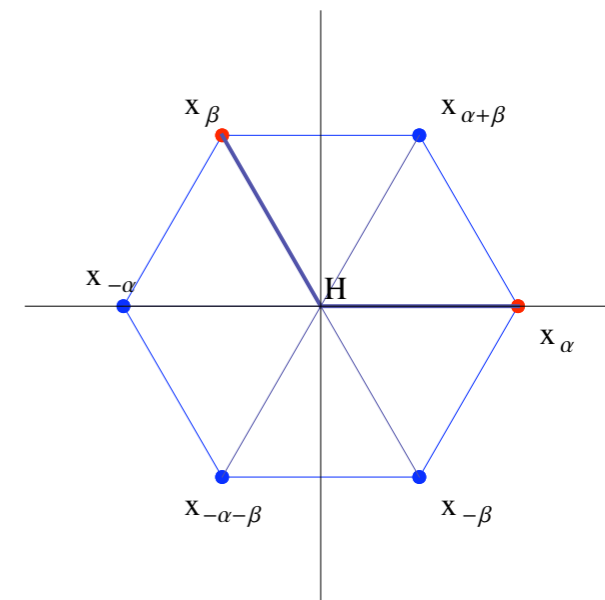
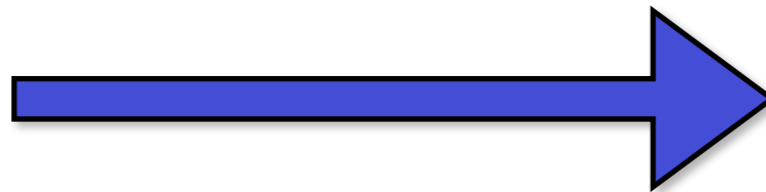
isomorphic!

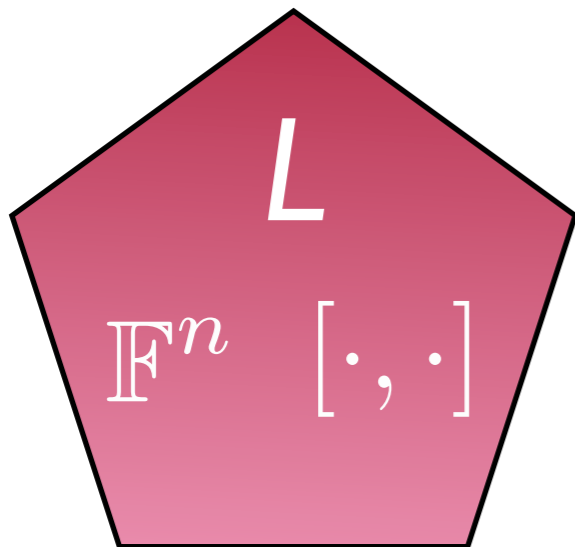
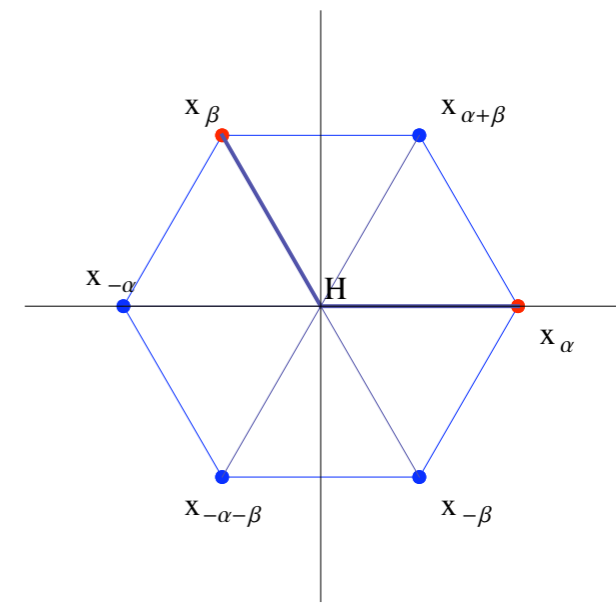
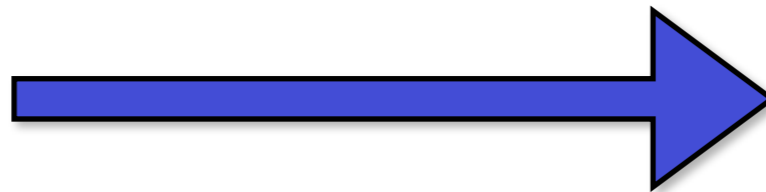


equal

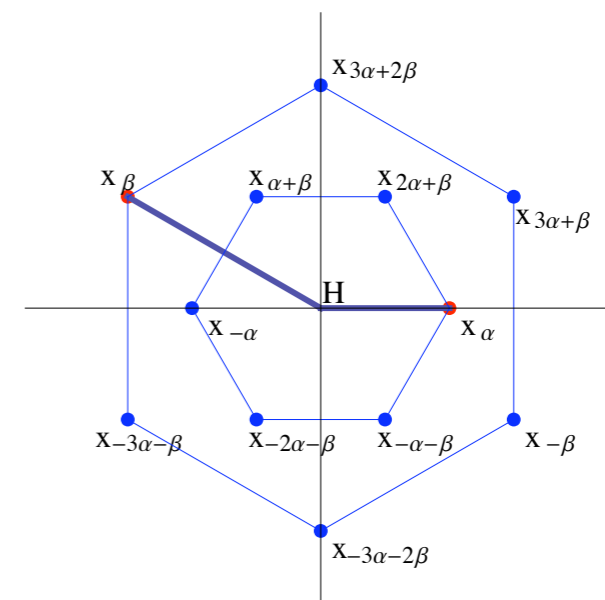
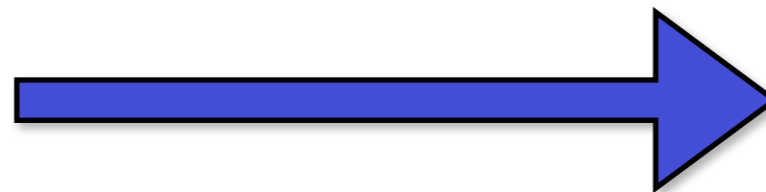
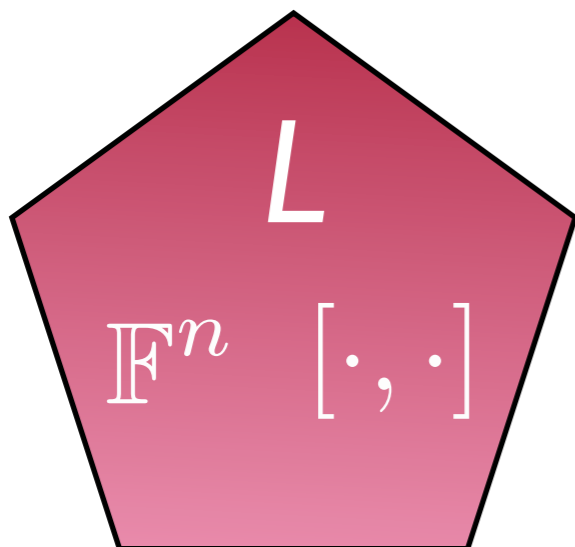
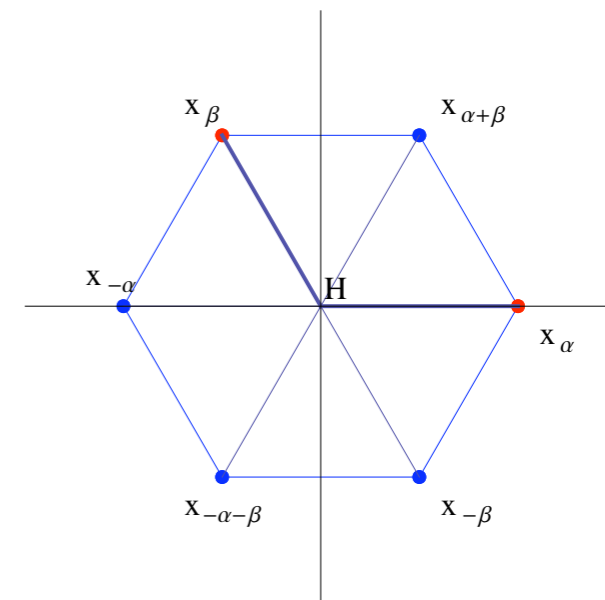
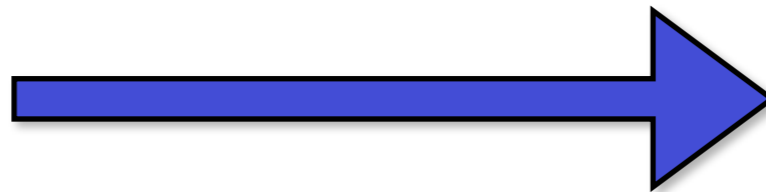


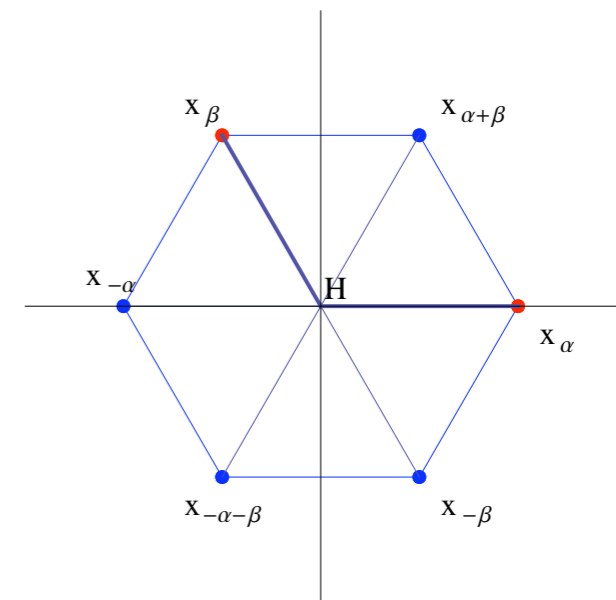
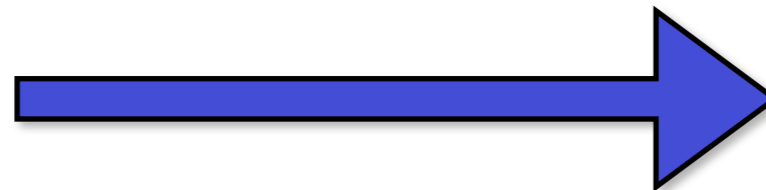
# Why?



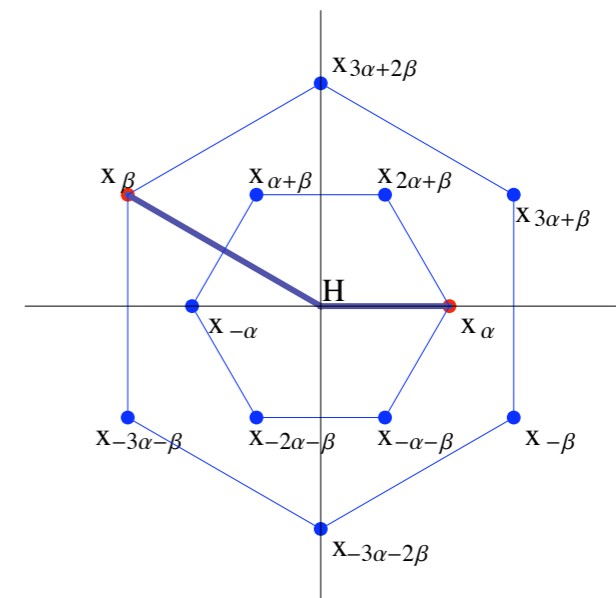
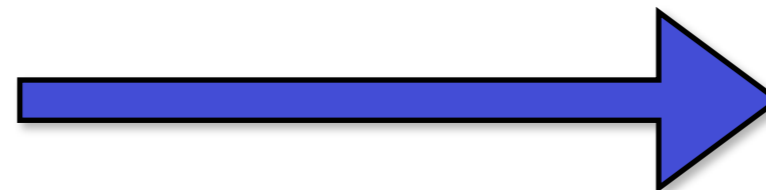
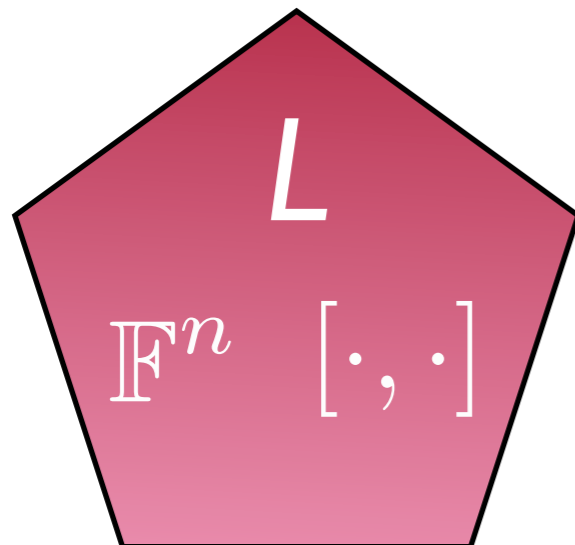


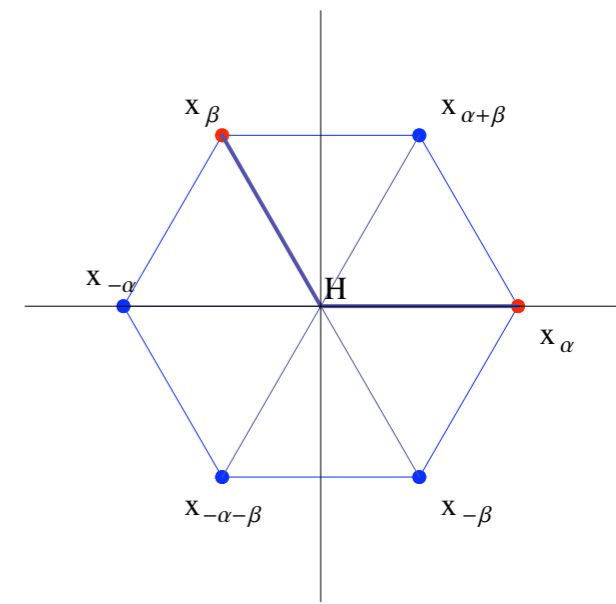
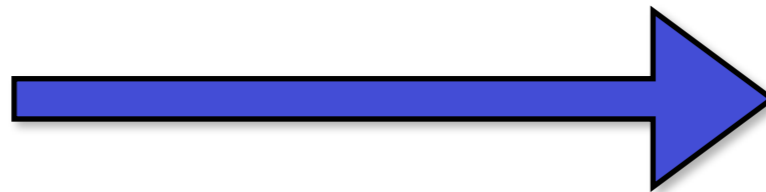




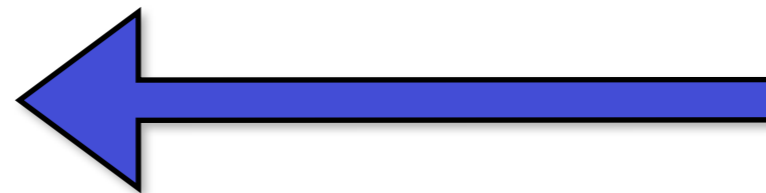


not equal

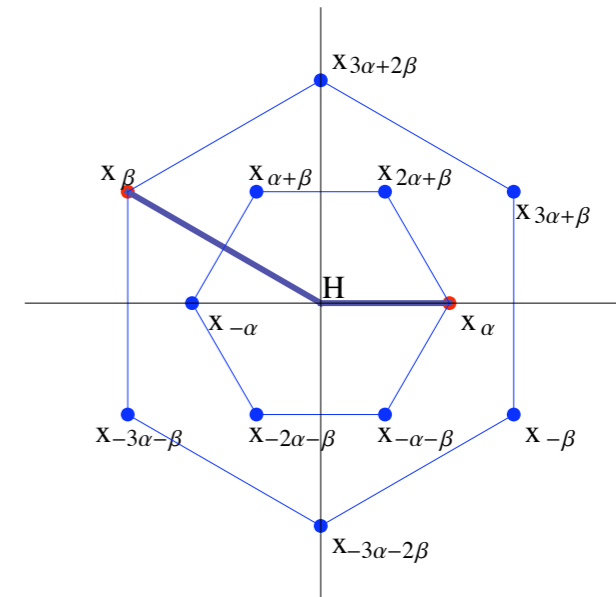
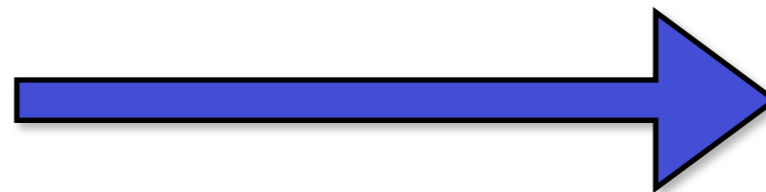
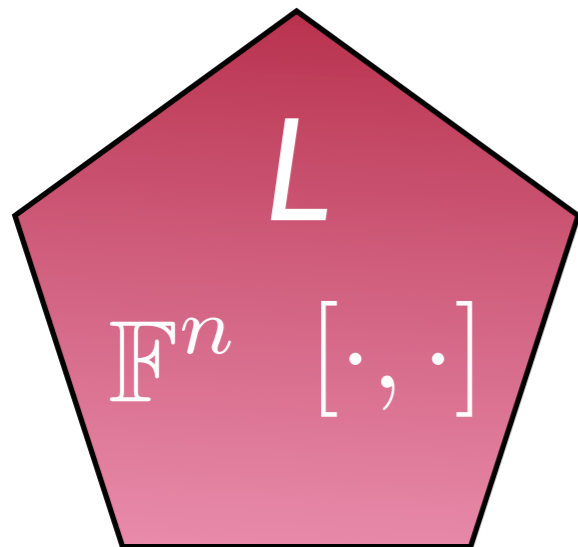




**non-isomorphic!**

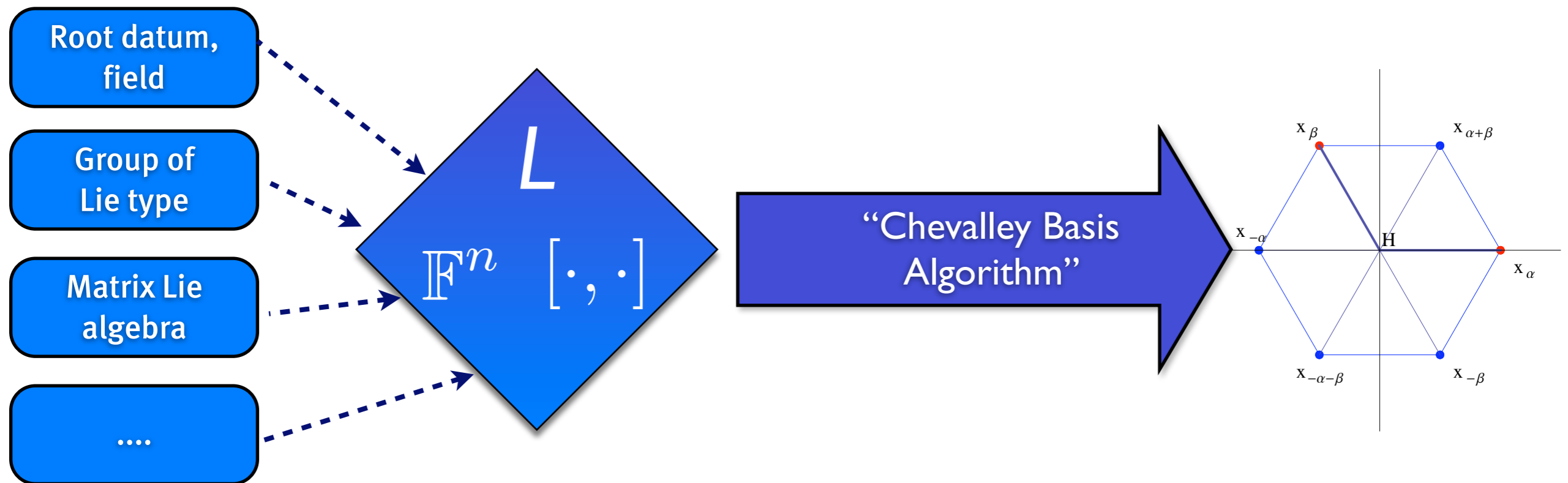


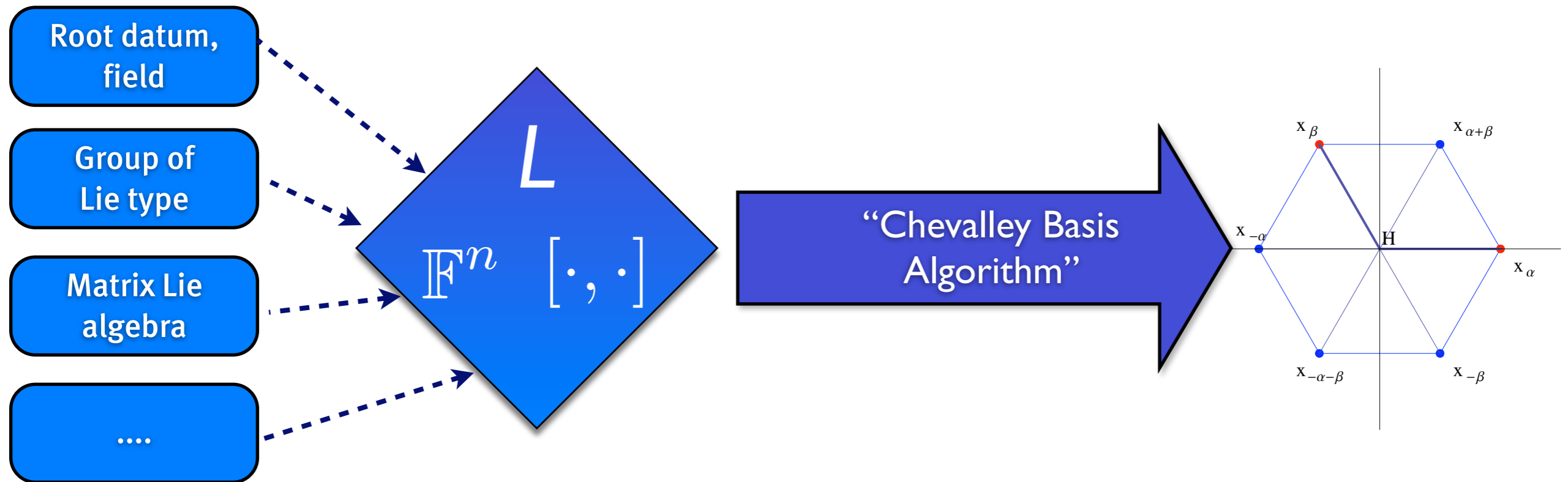
**not equal**



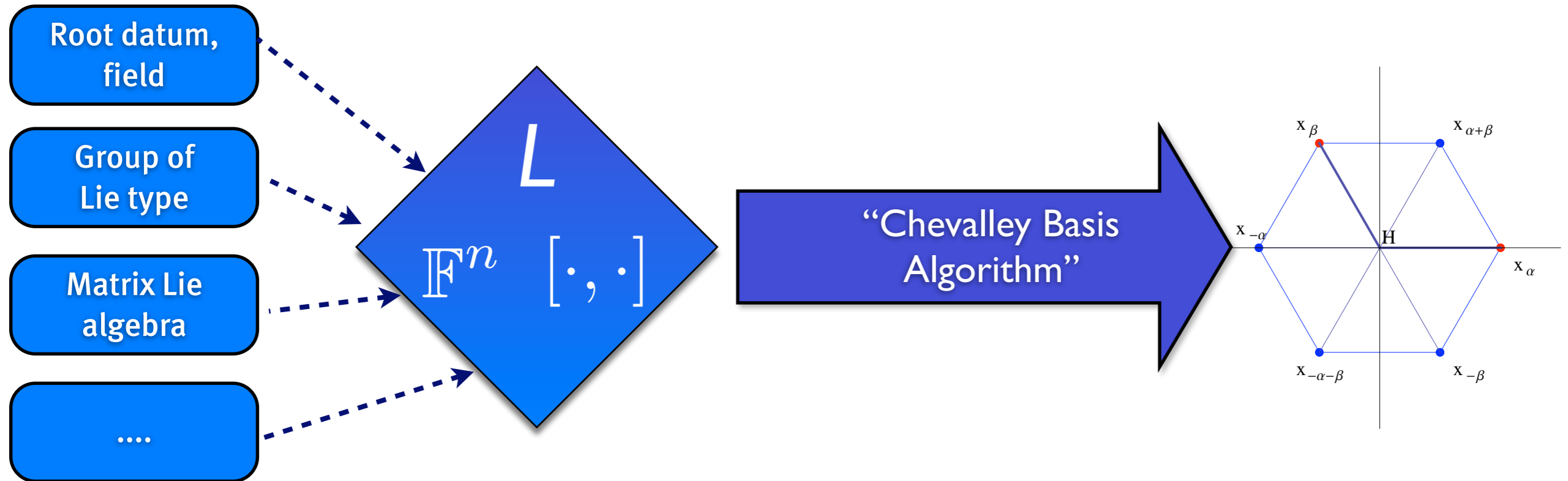
- ▶ What is a Lie algebra?
- ▶ What is a Chevalley basis?
- ▶ **How to compute Chevalley bases?**
- ▶ **What next?**

- ▶ Given a Lie algebra (on a computer),
- ▶ Want to know which Lie algebra it is,
- ▶ So want to compute a Chevalley basis for it (if possible).

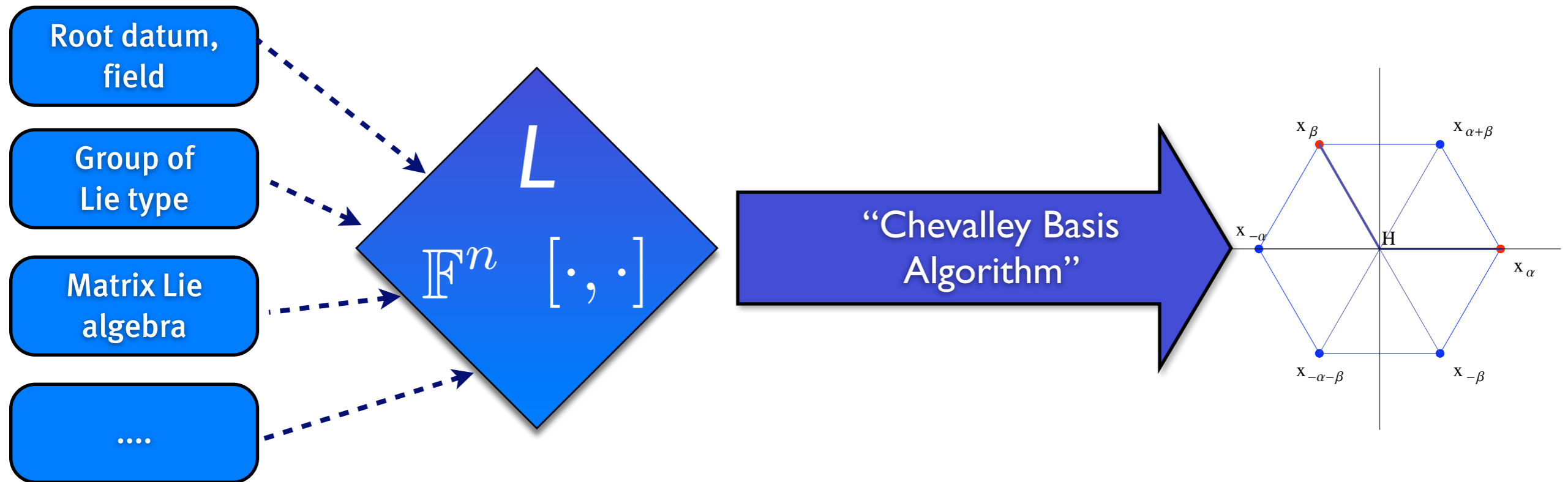




- ▶ Assume *splitting Cartan subalgebra*  $H$  is given (Cohen/Murray, indep. Ryba);
- ▶ Assume root datum  $R$  is given



- ▶ Char. 0,  $p \geq 5$ : De Graaf, Murray; implemented in GAP, MAGMA

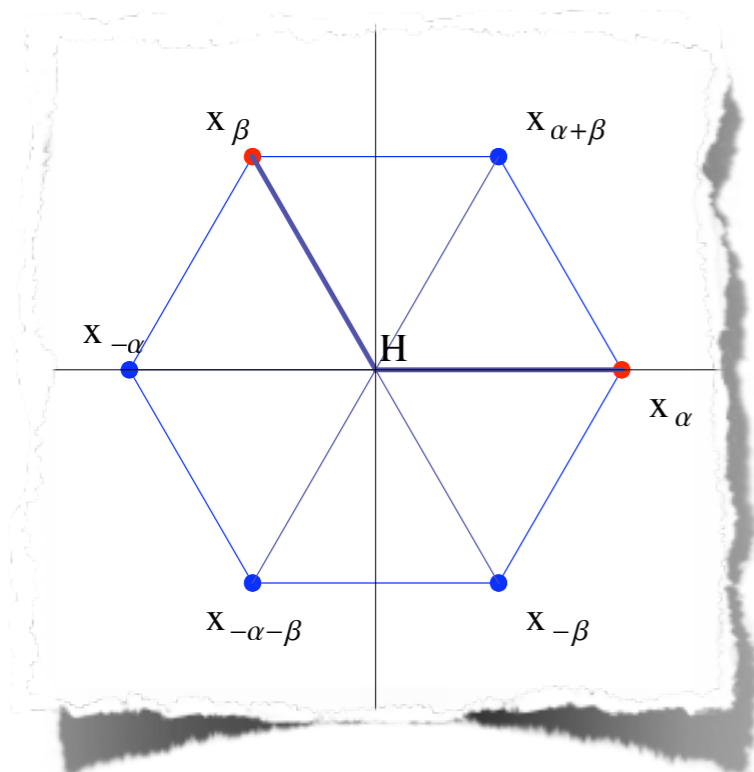


- ▶ Char. 0,  $p \geq 5$ : De Graaf, Murray; implemented in GAP, MAGMA
- ▶ Char. 2,3: R., 2009, Implemented in MAGMA



## Normally:

- ▶ Diagonalise  $L$  using action of  $H$  on  $L$  (gives set of  $x_\alpha$ ),
- ▶ Use Cartan integers  $\langle \alpha, \beta \rangle$  to “identify” the  $x_\alpha$ ,
- ▶ Solve easy linear equations.

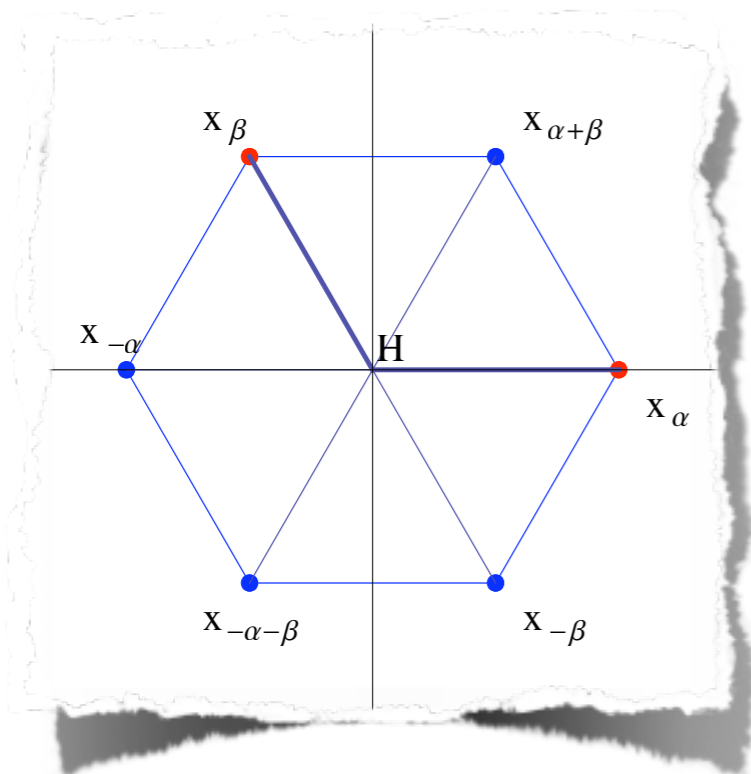


$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

## Normally:

- ▶ Diagonalise L using action of H on L (gives set of  $x_\alpha$ ),
- ▶ Use Cartan integers  $\langle \alpha, \beta \rangle$  to “identify” the  $x_\alpha$ ,
- ✓ ▶ Solve easy linear equations.

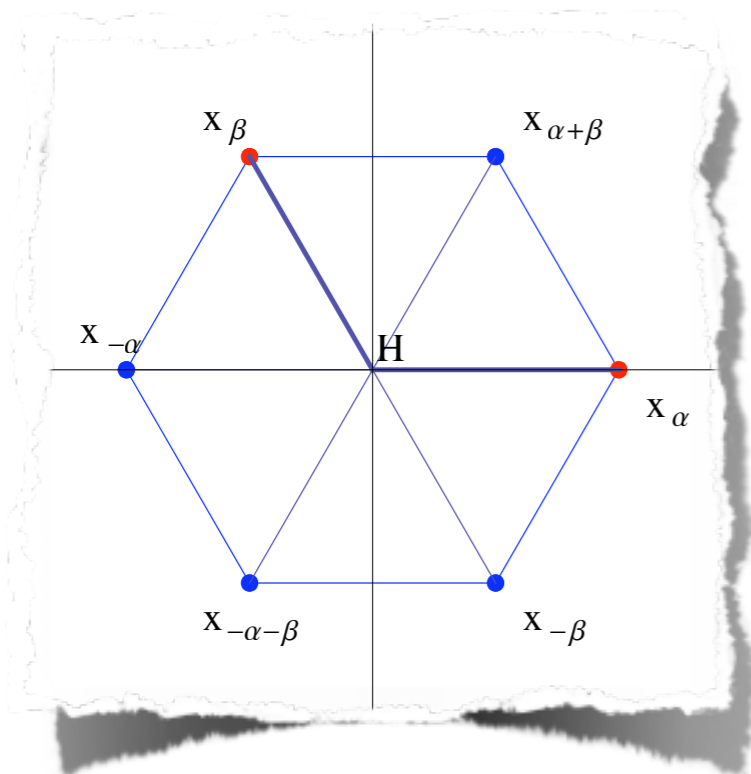


$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

## Normally:

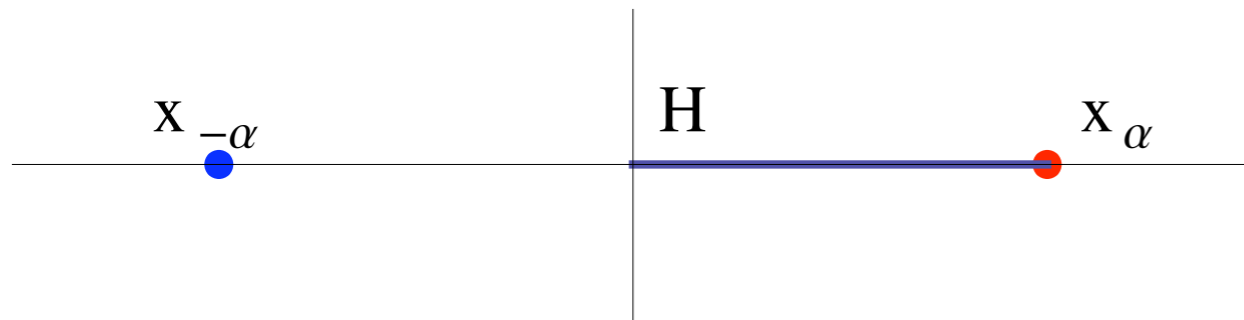
- ✗ ▶ Diagonalise  $L$  using action of  $H$  on  $L$  (gives set of  $x_\alpha$ ),
- ✗ ▶ Use Cartan integers  $\langle \alpha, \beta \rangle$  to “identify” the  $x_\alpha$ ,
- ✓ ▶ Solve easy linear equations.



$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

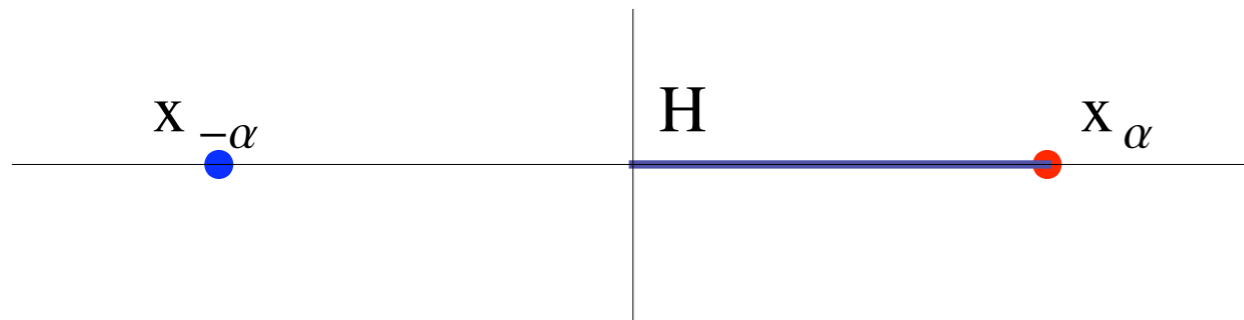
# Diagonalising ( $A_1$ , char. 2)



$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_{\alpha}, h_i] &= \langle \alpha, f_i \rangle x_{\alpha}, \\ [x_{-\alpha}, x_{\alpha}] &= \sum_{i=1}^n \langle e_i, \alpha^{\vee} \rangle h_i, \\ [x_{\alpha}, x_{\beta}] &= \begin{cases} N_{\alpha, \beta} x_{\alpha + \beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

# Diagonalising ( $A_1$ , char. 2)



$$A_1^{\text{Ad}} : X = Y = \mathbb{Z}$$

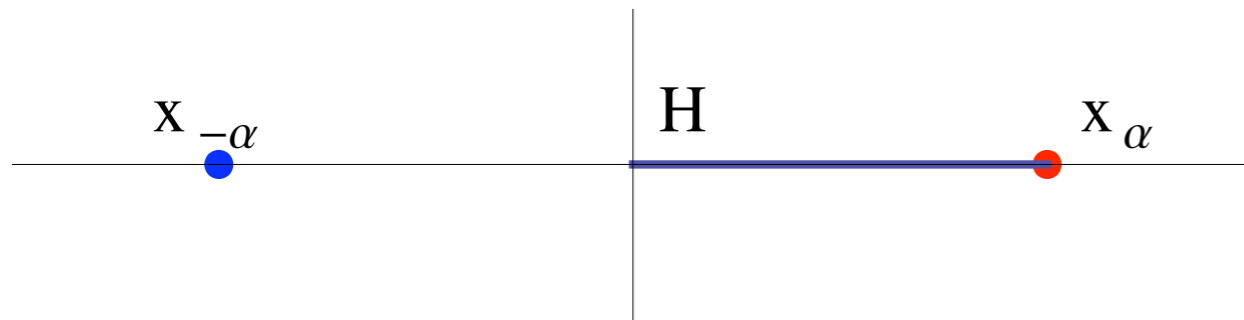
$$\Phi = \{\alpha = 1, -\alpha = -1\},$$

$$\Phi^\vee = \{\alpha^\vee = 2, -\alpha^\vee = -2\},$$

$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

# Diagonalising ( $A_1$ , char. 2)



$$\Lambda_1^{\text{Ad}} : X = Y = \mathbb{Z}$$

$$\Phi = \{\alpha = 1, -\alpha = -1\},$$

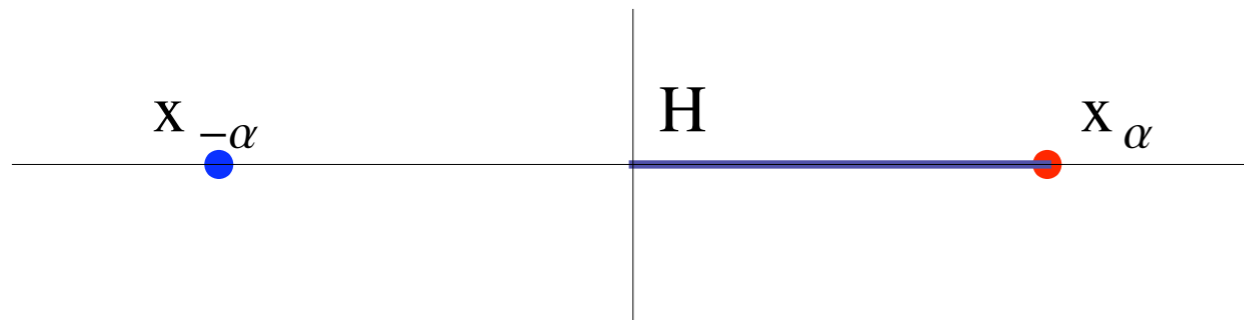
$$\Phi^\vee = \{\alpha^\vee = 2, -\alpha^\vee = -2\},$$

$$L = \mathbb{F}h \oplus \mathbb{F}x_\alpha \oplus \mathbb{F}x_{-\alpha}$$

$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

# Diagonalising ( $A_1$ , char. 2)



$$\Lambda_1^{\text{Ad}} : X = Y = \mathbb{Z}$$

$$\Phi = \{\alpha = 1, -\alpha = -1\},$$

$$\Phi^\vee = \{\alpha^\vee = 2, -\alpha^\vee = -2\},$$

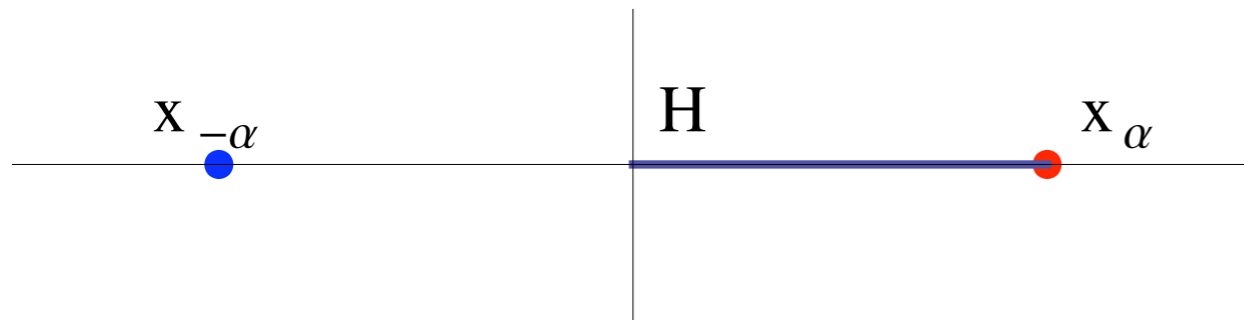
$$L = \mathbb{F}h \oplus \mathbb{F}x_\alpha \oplus \mathbb{F}x_{-\alpha}$$

$$\begin{aligned} [h_i, h_j] &= 0, \\ [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\ [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\ [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases} \end{aligned}$$

and the Jacobi identity.

	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$\langle e_1, \alpha^\vee \rangle h$	$\langle \alpha, f_1 \rangle x_\alpha$
$x_{-\alpha}$		0	$\langle -\alpha, f_1 \rangle x_{-\alpha}$
$h$			0

# Diagonalising ( $A_1$ , char. 2)



$$\Lambda_1^{\text{Ad}} : X = Y = \mathbb{Z}$$

$$\Phi = \{\alpha = 1, -\alpha = -1\},$$

$$\Phi^\vee = \{\alpha^\vee = 2, -\alpha^\vee = -2\},$$

$$L = \mathbb{F}h \oplus \mathbb{F}x_\alpha \oplus \mathbb{F}x_{-\alpha}$$

$$\begin{aligned}
 [h_i, h_j] &= 0, \\
 [x_\alpha, h_i] &= \langle \alpha, f_i \rangle x_\alpha, \\
 [x_{-\alpha}, x_\alpha] &= \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i, \\
 [x_\alpha, x_\beta] &= \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise,} \end{cases}
 \end{aligned}$$

and the Jacobi identity.

	$x_\alpha$	$x_{-\alpha}$	$h$	→		$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$\langle e_1, \alpha^\vee \rangle h$	$\langle \alpha, f_1 \rangle x_\alpha$		$x_\alpha$	0	$-2h$	$x_\alpha$
$x_{-\alpha}$		0	$\langle -\alpha, f_1 \rangle x_{-\alpha}$		$x_{-\alpha}$	$2h$	0	$-x_{-\alpha}$
$h$			0		$h$	$-x_\alpha$	$x_{-\alpha}$	0

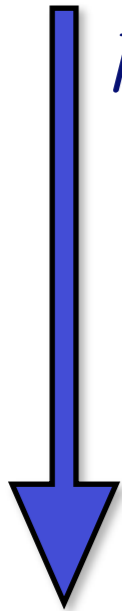


# Diagonalising ( $A_1$ , char. 2)

	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$-2h$	$x_\alpha$
$x_{-\alpha}$	$2h$	0	$-x_{-\alpha}$
$h$	$-x_\alpha$	$x_{-\alpha}$	0

# Diagonalising ( $A_1$ , char. 2)

	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$-2h$	$x_\alpha$
$x_{-\alpha}$	$2h$	0	$-x_{-\alpha}$
$h$	$-x_\alpha$	$x_{-\alpha}$	0



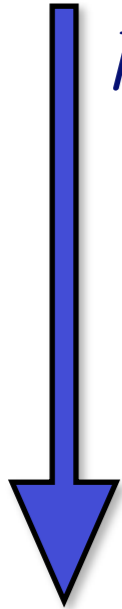
**Basis transformation....**

$$x = x_\alpha - x_{-\alpha}$$

$$y = 2x_\alpha + x_{-\alpha}$$

# Diagonalising ( $A_1$ , char. 2)

	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$-2h$	$x_\alpha$
$x_{-\alpha}$	$2h$	0	$-x_{-\alpha}$
$h$	$-x_\alpha$	$x_{-\alpha}$	0



**Basis transformation....**

$$x = x_\alpha - x_{-\alpha}$$

$$y = 2x_\alpha + x_{-\alpha}$$

	$x$	$y$	$h$
$x$	0	$-6h$	$-\frac{1}{3}x + \frac{2}{3}y$
$y$	$6h$	0	$\frac{4}{3}x + \frac{1}{3}y$
$h$	$\frac{1}{3}x - \frac{2}{3}y$	$-\frac{4}{3}x - \frac{1}{3}y$	0

# Diagonalising (A<sub>1</sub>, char. 2)

	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$-2h$	$x_\alpha$
$x_{-\alpha}$	$2h$	0	$-x_{-\alpha}$
$h$	$-x_\alpha$	$x_{-\alpha}$	0

**Basis transformation....**

$$x = x_\alpha - x_{-\alpha}$$

$$y = 2x_\alpha + x_{-\alpha}$$

	$x$	$y$	$h$
$x$	0	$-6h$	$-\frac{1}{3}x + \frac{2}{3}y$
$y$	$6h$	0	$\frac{4}{3}x + \frac{1}{3}y$
$h$	$\frac{1}{3}x - \frac{2}{3}y$	$-\frac{4}{3}x - \frac{1}{3}y$	0

**Algorithm:**

- ▶ Diagonalize L wrt H
- ▶ Find 1-dim eigenspaces:

$$S_1, S_{-1}, S_0$$

- ▶ Take

$$\begin{aligned} x + y &\in S_1 \\ x - \frac{1}{2}y &\in S_{-1} \\ h &\in S_0 \end{aligned}$$

- ▶ Done!

## Algorithm:

- ▶ Diagonalize  $L$  wrt  $H$
- ▶ Find 1-dim eigenspaces:

$$S_1, S_{-1}, S_0$$

- ▶ Take

$$\begin{aligned}x + y &\in S_1 \\x - \frac{1}{2}y &\in S_{-1} \\h &\in S_0\end{aligned}$$

- ▶ Done!

## Algorithm:

- ▶ Diagonalize  $L$  wrt  $H$
- ▶ Find 1-dim eigenspaces:

$$S_1, S_{-1}, S_0$$

- ▶ Take

$$\begin{aligned}x + y &\in S_1 \\x - \frac{1}{2}y &\in S_{-1} \\h &\in S_0\end{aligned}$$

- ▶ Done!

## But in char. 2...

- ▶ Diagonalize  $L$  wrt  $H$
- ▶ Find 1-dim eigenspace:  $S_0$
- ▶ Find 2-dim eigenspace:  $S_1$
- ▶ ...

## Algorithm:

- ▶ Diagonalize  $L$  wrt  $H$
- ▶ Find 1-dim eigenspaces:

$$S_1, S_{-1}, S_0$$

- ▶ Take

$$\begin{aligned}x + y &\in S_1 \\x - \frac{1}{2}y &\in S_{-1} \\h &\in S_0\end{aligned}$$

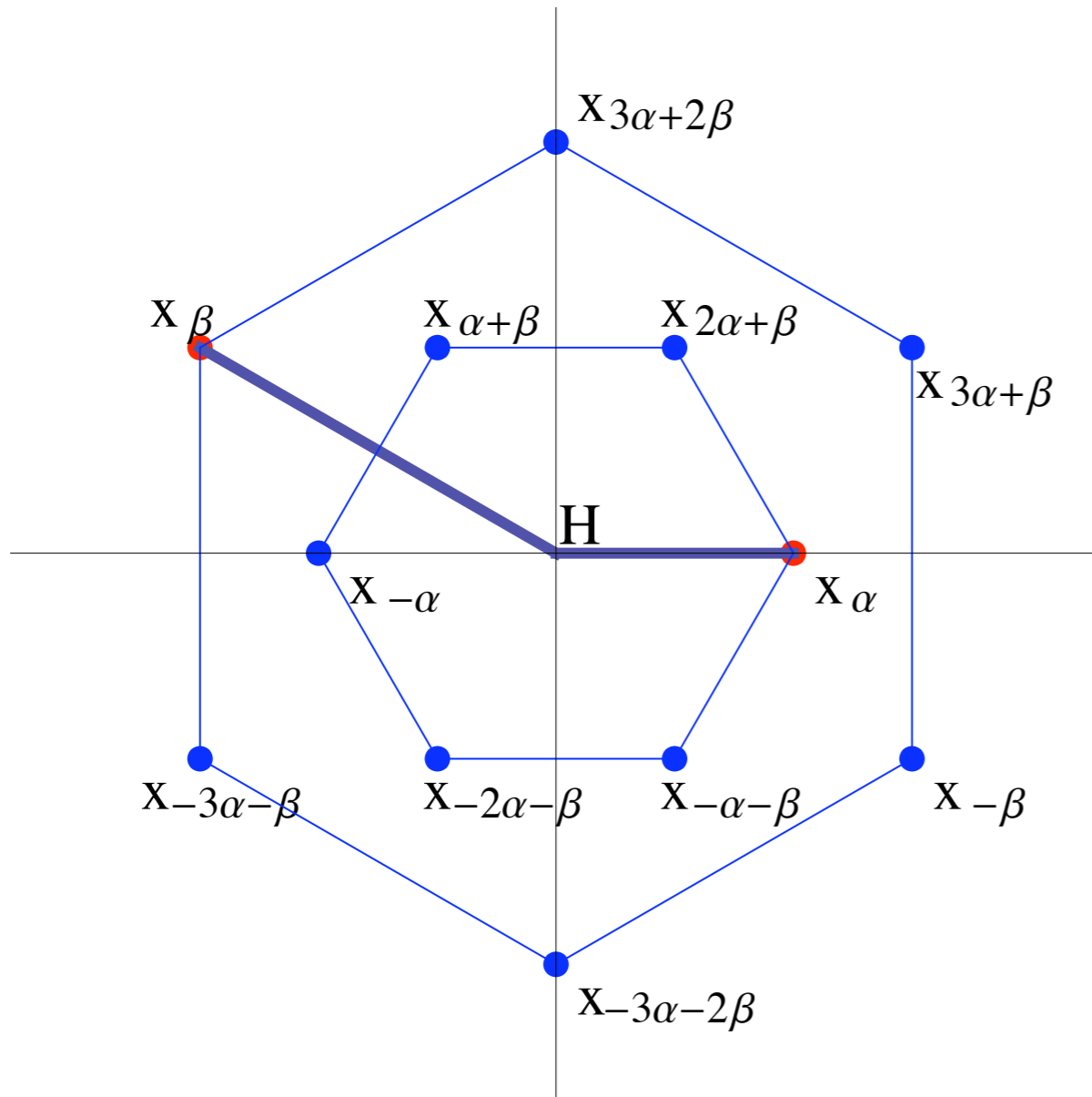
- ▶ Done!

## But in char. 2...

- ▶ Diagonalize  $L$  wrt  $H$
- ▶ Find 1-dim eigenspace:  $S_0$
- ▶ Find 2-dim eigenspace:  $S_1$
- ▶ ...

- ▶ Not really an issue here (almost anything will do), but non-trivial in many other cases.

# Diagonalising ( $G_2$ , char. 3)



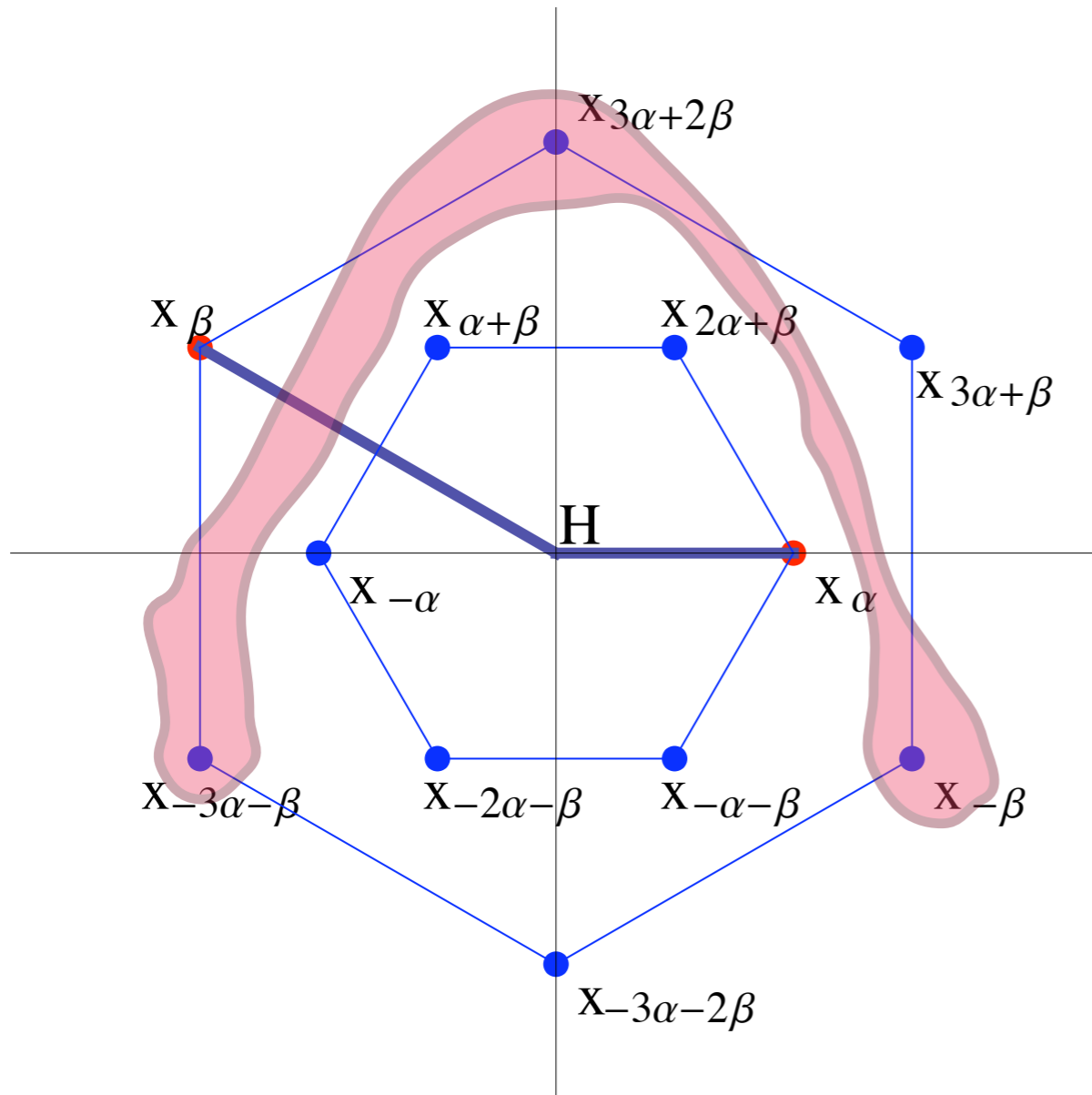




# Diagonalising ( $G_2$ , char. 3)

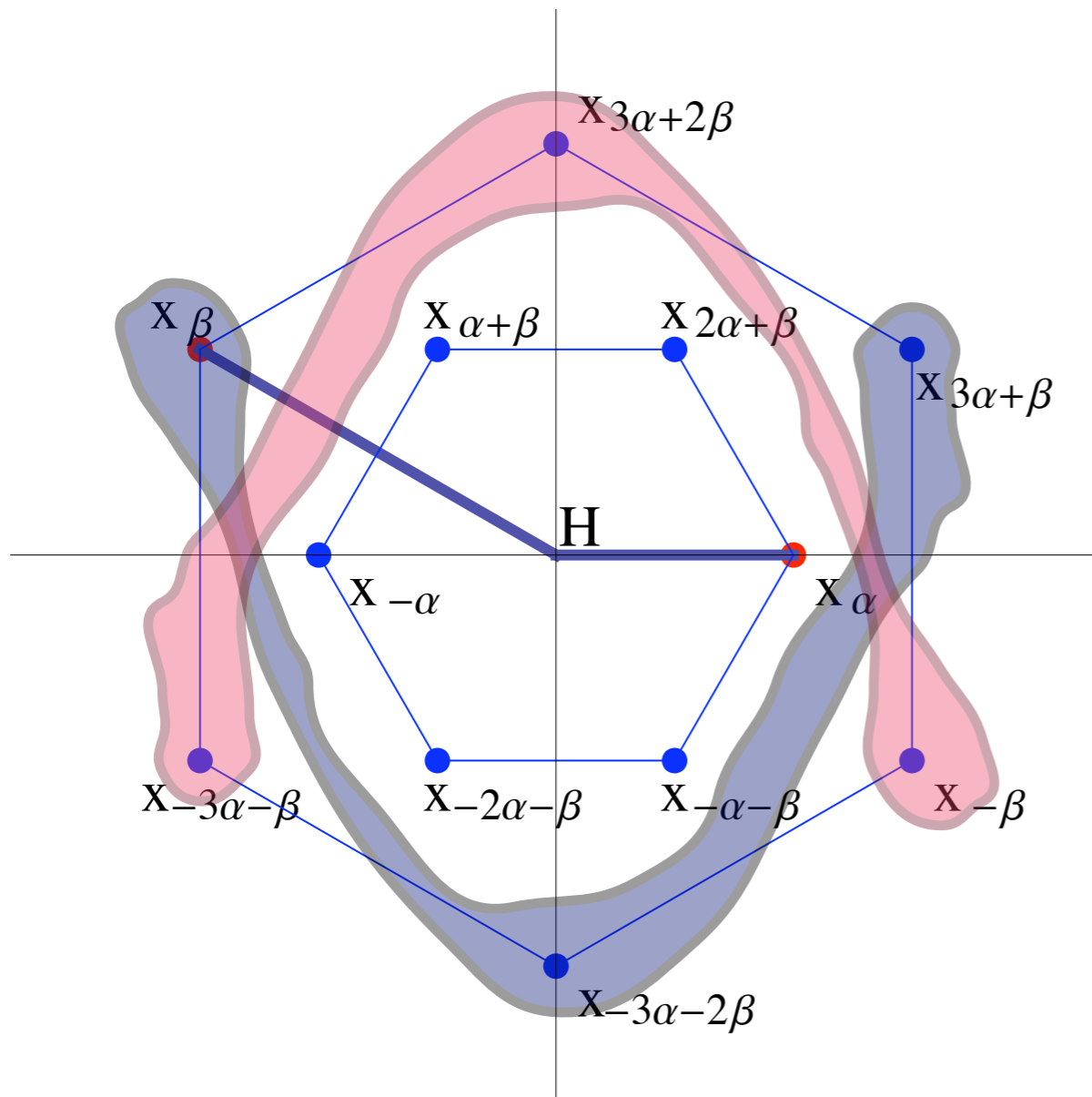
In char. 3...

- ▶ Find 1 2-dim eigenspace,
- ▶ Find 6 1-dim eigenspaces,
- ▶ Find 2 3-dim eigenspaces.



In char. 3...

- ▶ Find 1 2-dim eigenspace,
- ▶ Find 6 1-dim eigenspaces,
- ▶ Find 2 3-dim eigenspaces.







# Diagonalising (overview)

$R(p)$	Mults	Soln	$R(p)$	Mults	Soln
$A_2^{sc}(3)$	$3^2$	[Der]	$C_n^{ad}(2) (n \geq 3)$	$2n, 2^{n(n-1)}$	[C]
$G_2(3)$	$1^6, 3^2$	[C]	$C_n^{sc}(2) (n \geq 3)$	$2n, 4^{\binom{n}{2}}$	$[B_2^{sc}]$
$A_3^{sc,(2)}(2)$	$4^3$	[Der]	$D_4^{(1),(n-1),(n)}(2)$	$4^6$	[Der]
$B_2^{ad}(2)$	$2^2, 4$	[C]	$D_4^{sc}(2)$	$8^3$	[Der]
$B_n^{ad}(2) (n \geq 3)$	$2^n, 4^{\binom{n}{2}}$	[C]	$D_n^{(1)}(2) (n \geq 5)$	$4^{\binom{n}{2}}$	[Der]
$B_2^{sc}(2)$	$4, 4$	$[B_2^{sc}]$	$D_n^{sc}(2) (n \geq 5)$	$4^{\binom{n}{2}}$	[Der]
$B_3^{sc}(2)$	$6^3$	[Der]	$F_4(2)$	$2^{12}, 8^3$	[C]
$B_4^{sc}(2)$	$2^4, 8^3$	[Der]	$G_2(2)$	$4^3$	[Der]
$B_n^{sc}(2) (n \geq 5)$	$2^n, 4^{\binom{n}{2}}$	[C]	all remaining(2)	$2^{ \Phi^+ }$	$[A_2]$

TABLE 1. Multidimensional root spaces



# Diagonalising (overview)

$R(p)$	Mults	Soln	$R(p)$	Mults	Soln
$A_2^{sc}(3)$	$3^2$	[Der]	$C_n^{ad}(2) (n \geq 3)$	$2n, 2^{n(n-1)}$	[C]
<b><math>G_2(3)</math></b>	<b><math>1^6, 3^2</math></b>	<b>[C]</b>	$C_n^{sc}(2) (n \geq 3)$	<b><math>2n, 4^{\binom{n}{2}}</math></b>	<b><math>[B_2^{sc}]</math></b>
$A_3^{sc,(2)}(2)$	$4^3$	[Der]	$D_4^{(1),(n-1),(n)}(2)$	$4^6$	[Der]
$B_2^{ad}(2)$	$2^2, 4$	[C]	$D_4^{sc}(2)$	$8^3$	[Der]
$B_n^{ad}(2) (n \geq 3)$	$2^n, 4^{\binom{n}{2}}$	[C]	$D_n^{(1)}(2) (n \geq 5)$	$4^{\binom{n}{2}}$	[Der]
$B_2^{sc}(2)$	$4, 4$	$[B_2^{sc}]$	$D_n^{sc}(2) (n \geq 5)$	$4^{\binom{n}{2}}$	[Der]
$B_3^{sc}(2)$	$6^3$	[Der]	$F_4(2)$	$2^{12}, 8^3$	[C]
$B_4^{sc}(2)$	$2^4, 8^3$	[Der]	$G_2(2)$	$4^3$	[Der]
$B_n^{sc}(2) (n \geq 5)$	$2^n, 4^{\binom{n}{2}}$	[C]	<b>all remaining(2)</b>	<b><math>2^{ \Phi^+ }</math></b>	<b><math>[A_2]</math></b>

TABLE 1. Multidimensional root spaces



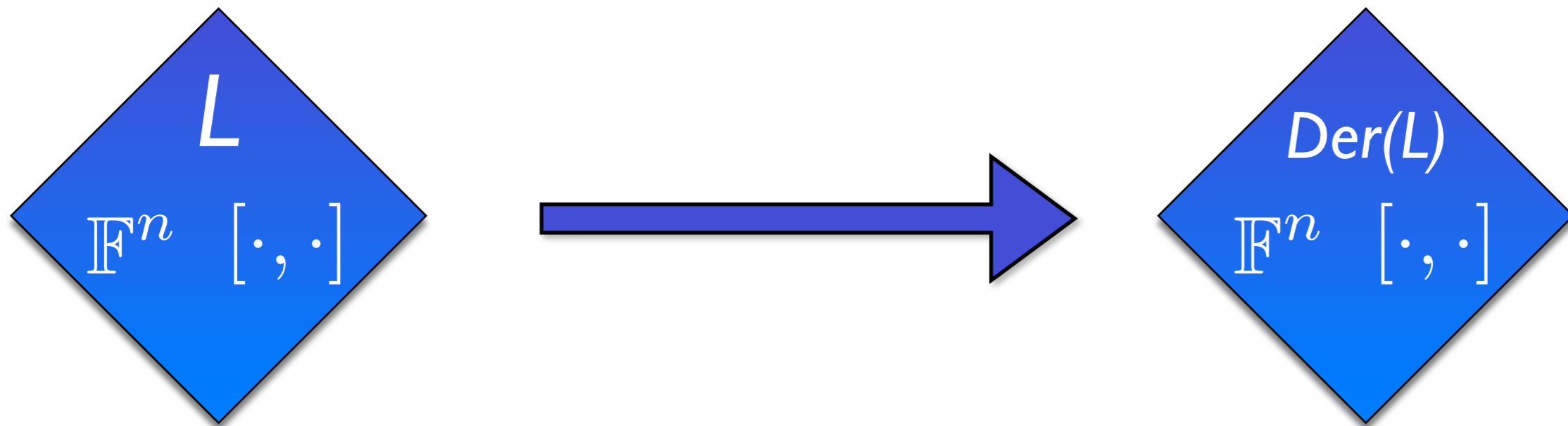
# Diagonalising (overview)

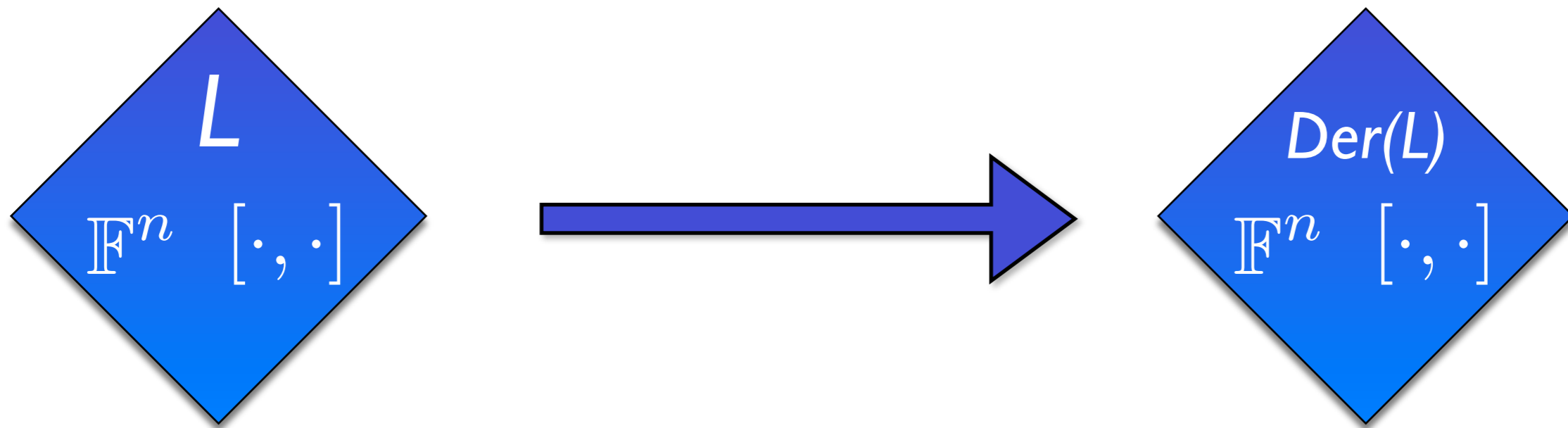
$R(p)$	Mults	Soln	$R(p)$	Mults	Soln
$A_2^{sc}(3)$	$3^2$	[Der]	$C_n^{ad}(2) (n \geq 3)$	$2n, 2^{n(n-1)}$	[C]
$G_2(3)$	$1^6, 3^2$	[C]	$C_n^{sc}(2) (n \geq 3)$	$2n, 4^{\binom{n}{2}}$	$[B_2^{sc}]$
$A_3^{sc,(2)}(2)$	$4^3$	[Der]	$D_4^{(1),(n-1),(n)}(2)$	$4^6$	[Der]
$B_2^{ad}(2)$	$2^2, 4$	[C]	$D_4^{sc}(2)$	$8^3$	[Der]
$B_n^{ad}(2) (n \geq 3)$	$2^n, 4^{\binom{n}{2}}$	[C]	$D_n^{(1)}(2) (n \geq 5)$	$4^{\binom{n}{2}}$	[Der]
$B_2^{sc}(2)$	$4, 4$	$[B_2^{sc}]$	$D_n^{sc}(2) (n \geq 5)$	$4^{\binom{n}{2}}$	[Der]
$B_3^{sc}(2)$	$6^3$	[Der]	$F_4(2)$	$2^{12}, 8^3$	[C]
$B_4^{sc}(2)$	$2^4, 8^3$	[Der]	$G_2(2)$	$4^3$	[Der]
$B_n^{sc}(2) (n \geq 5)$	$2^n, 4^{\binom{n}{2}}$	[C]	all remaining(2)	$2^{ \Phi^+ }$	$[A_2]$

TABLE 1. Multidimensional root spaces

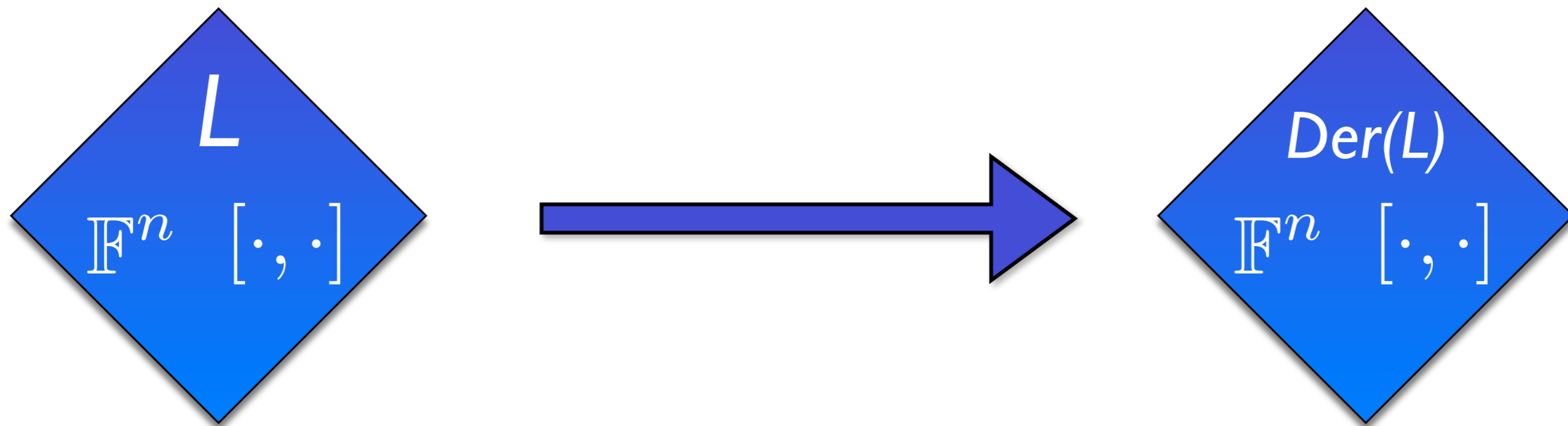




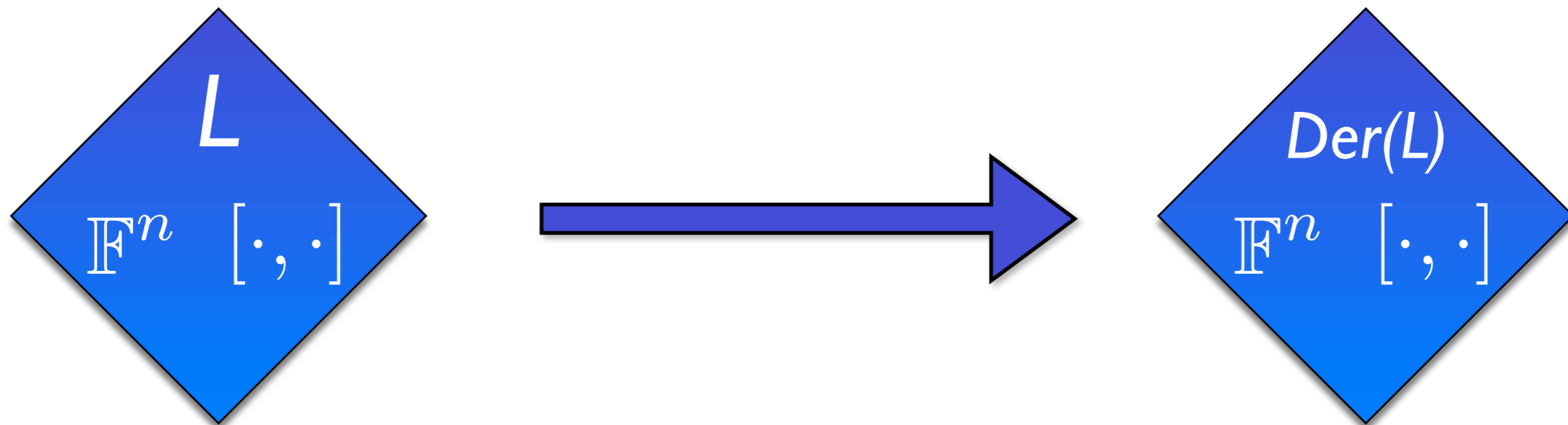




►  $\text{Der}(L) = \{d \in \text{End}(L) \mid d([x, y]) = [d(x), y] + [x, d(y)]\}$



- ▶  $\text{Der}(L) = \{d \in \text{End}(L) \mid d([x, y]) = [d(x), y] + [x, d(y)]\}$
- ▶ **Observe:**
  - $\text{Der}(L)$  is a Lie algebra
  - **(almost)**  $L \subseteq \text{Der}(L)$



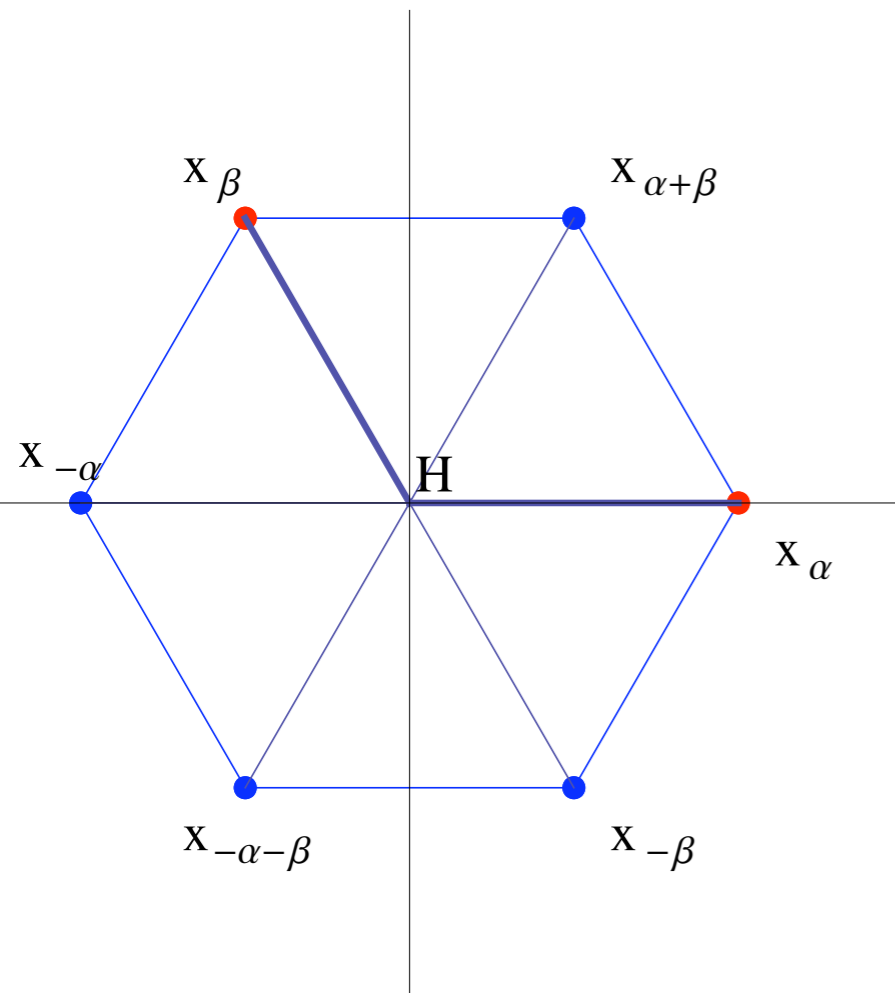
▶  $\text{Der}(L) = \{d \in \text{End}(L) \mid d([x, y]) = [d(x), y] + [x, d(y)]\}$

▶ **Observe:**

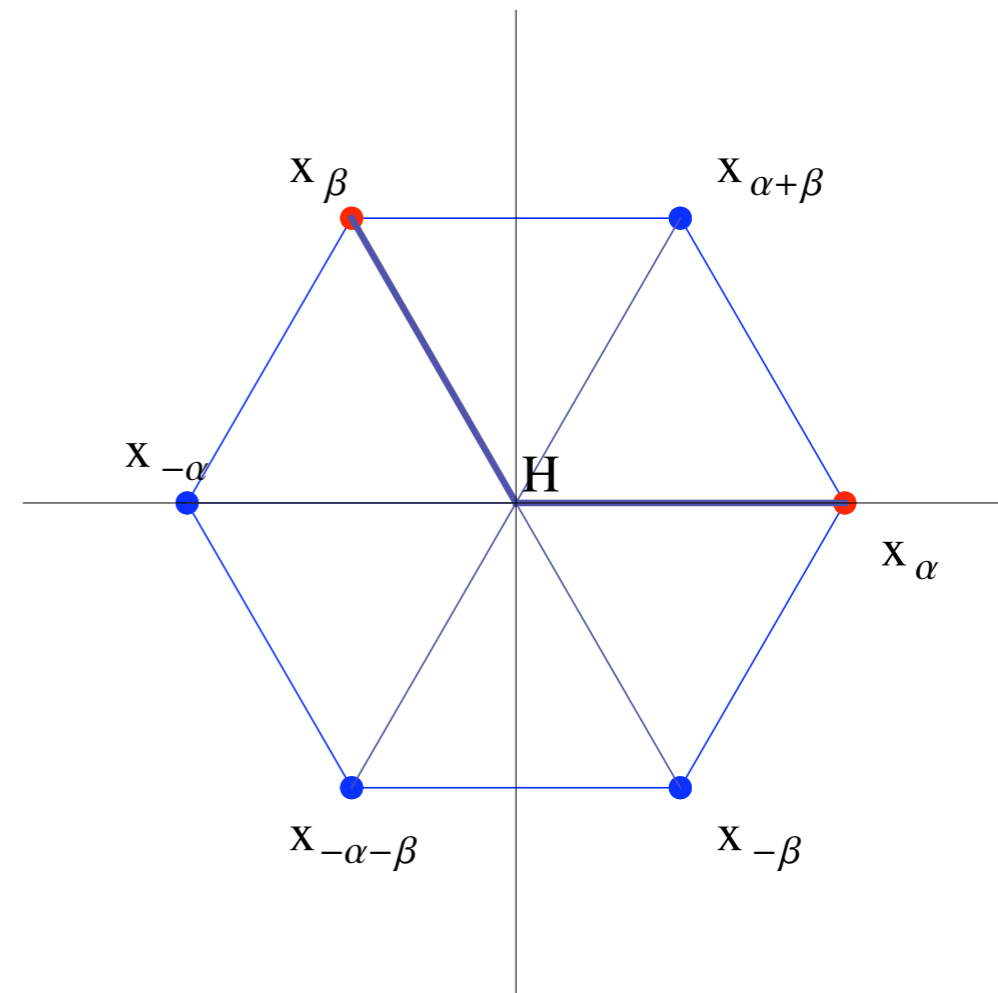
- $\text{Der}(L)$  is a Lie algebra
- (almost)  $L \subseteq \text{Der}(L)$

$$\begin{aligned}
 \text{ad}_z([x, y]) &= [z, [x, y]] \\
 &= -[x, [y, z]] - [y, [z, x]] \\
 &= [x, [z, y]] + [[z, x], y] \\
 &= [x, \text{ad}_z(y)] + [\text{ad}_z(x), y]
 \end{aligned}$$

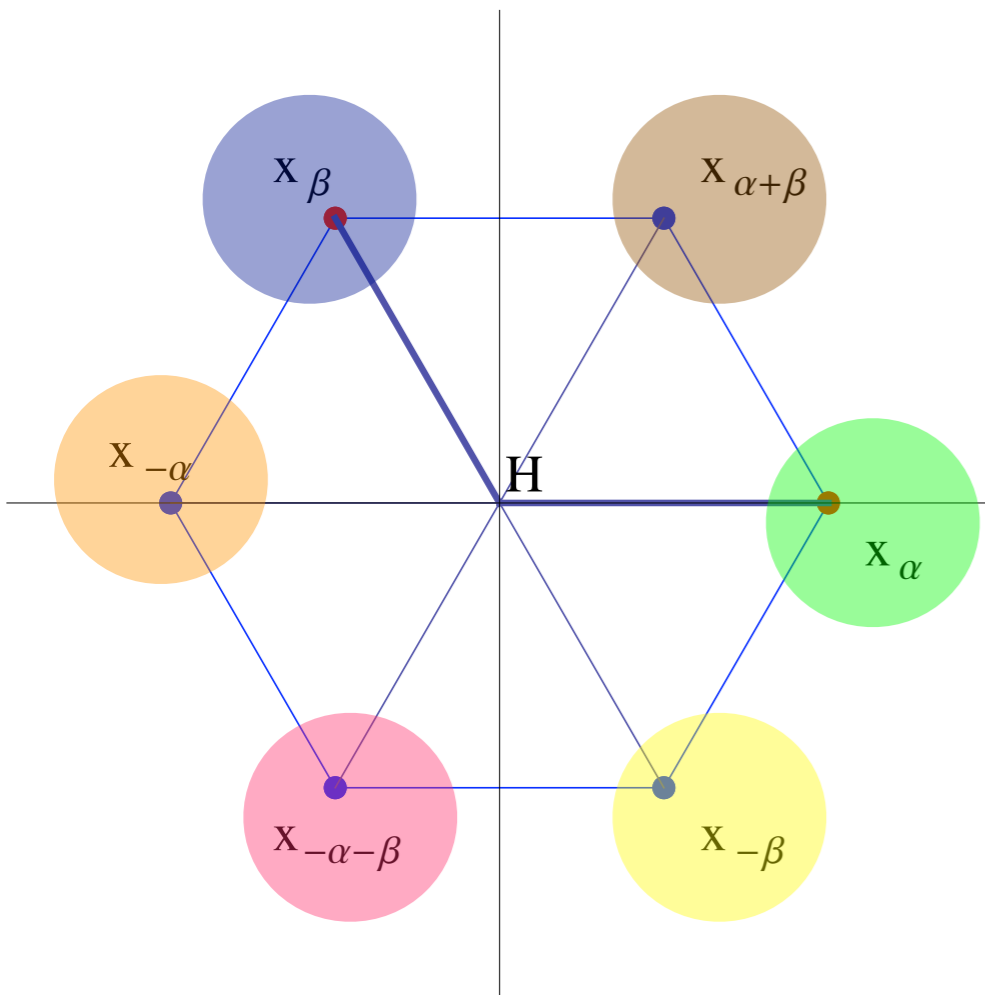
## Adjoint



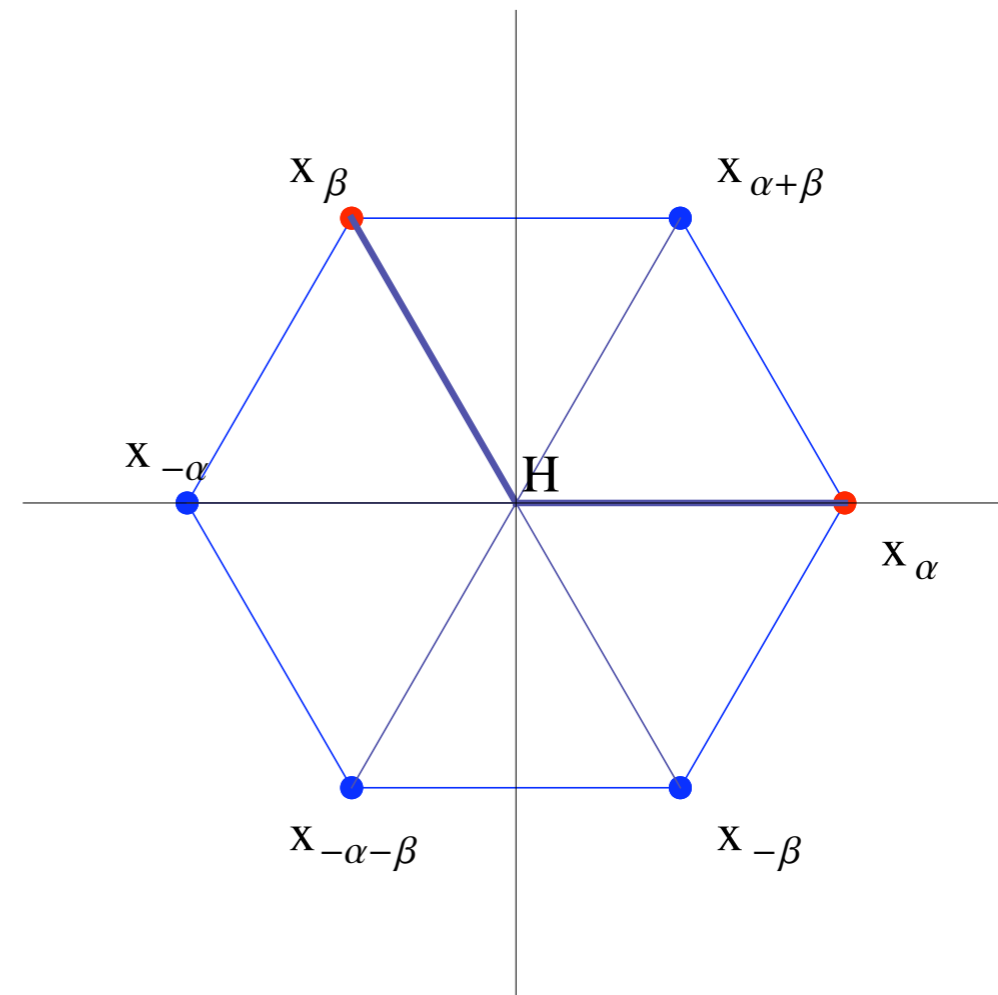
## Simply Connected



## Adjoint

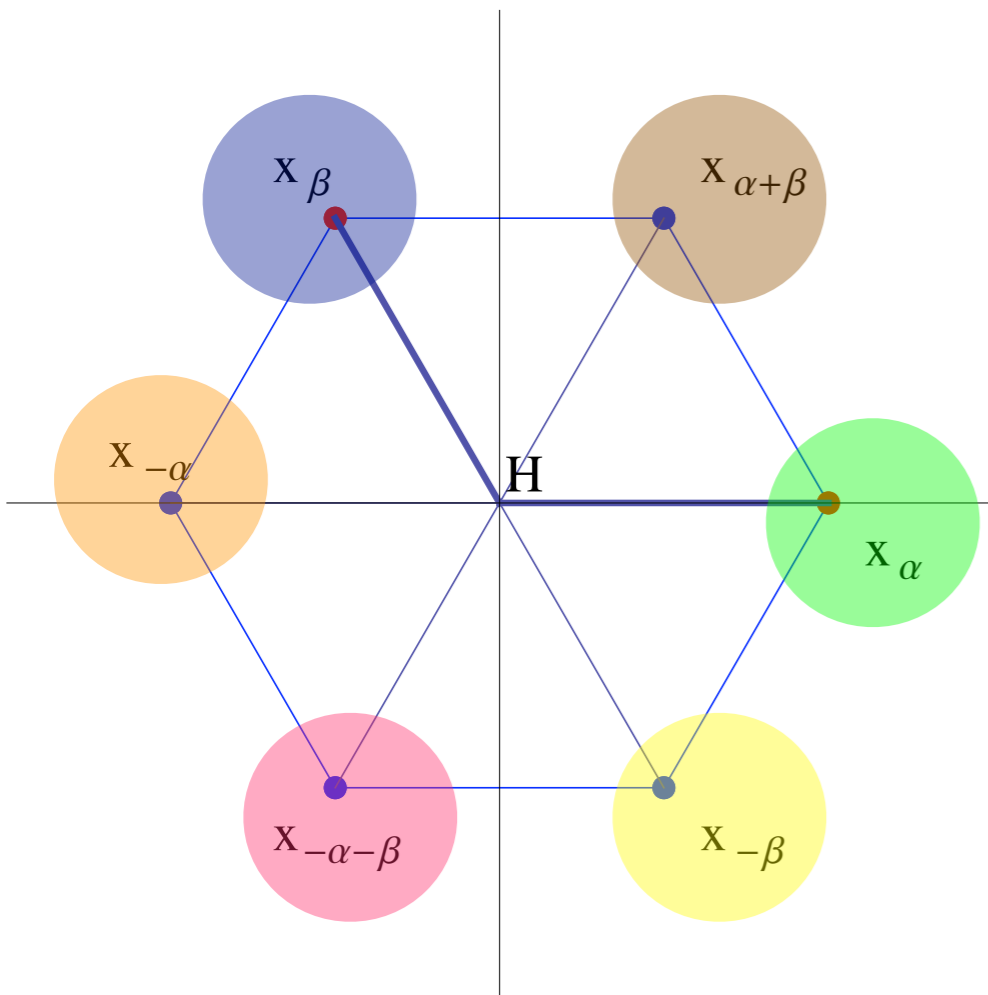


## Simply Connected



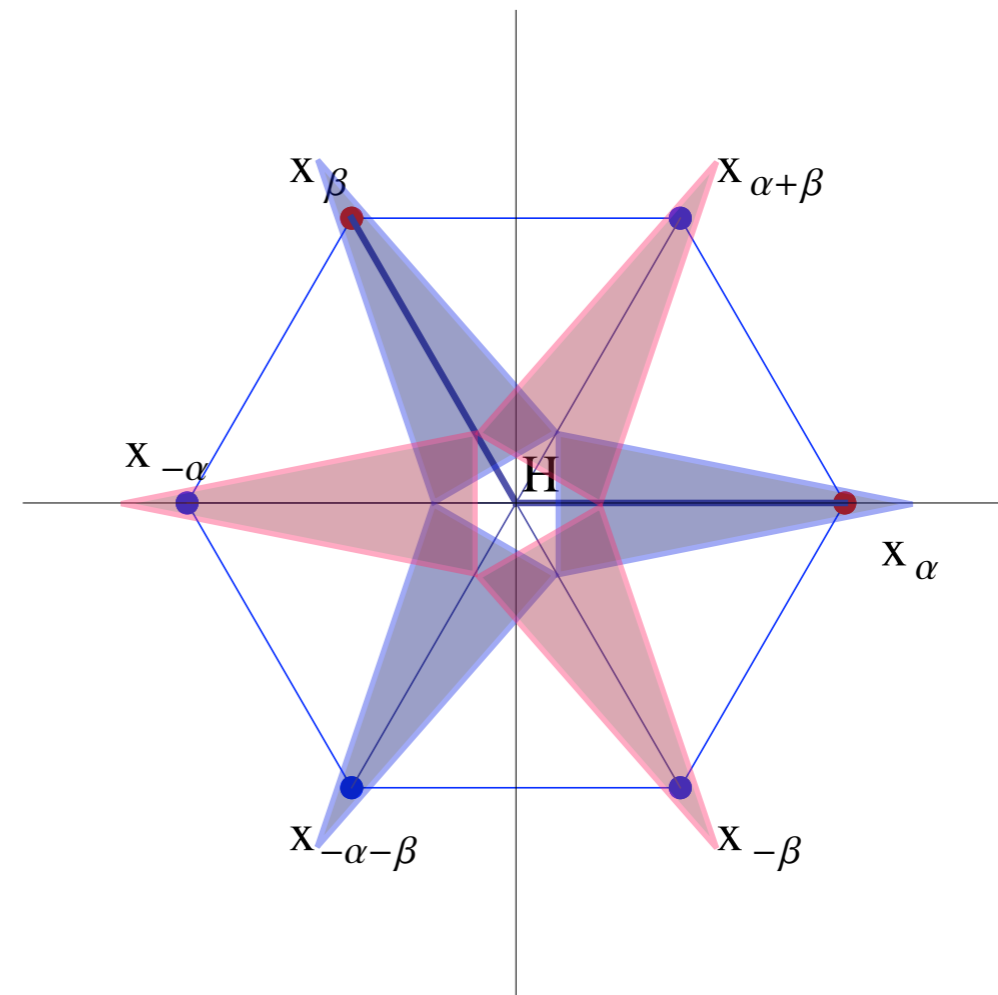
6 one-dimensional spaces

## Adjoint



6 one-dimensional spaces

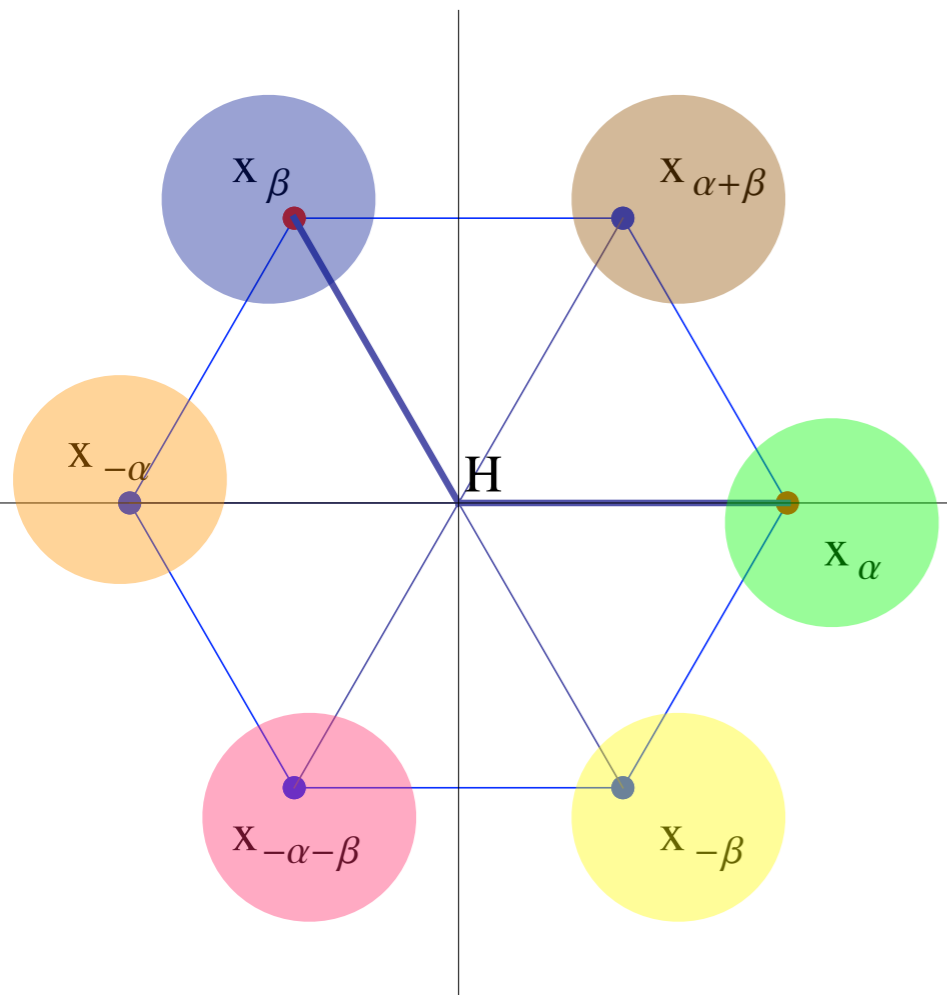
## Simply Connected



2 three-dimensional spaces

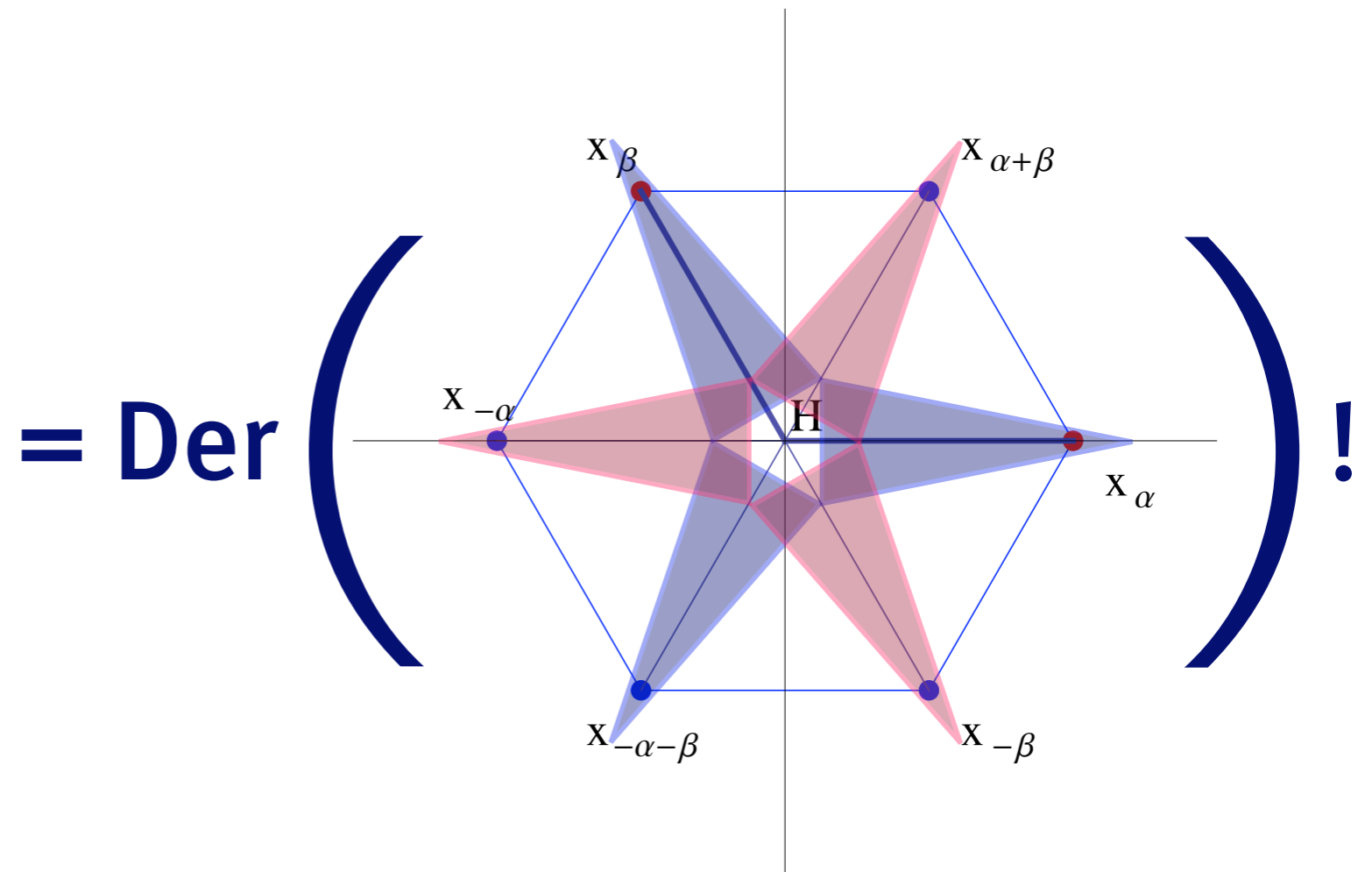
# Diagonalising ( $A_2$ , char. 3)

## Adjoint



6 one-dimensional spaces

## Simply Connected



2 three-dimensional spaces



- ▶ What is a Lie algebra?
- ▶ What is a Chevalley basis?
- ▶ How to compute Chevalley bases?
- ▶ **What next?**

- ▶ **Main challenges for computing Chevalley bases in small characteristic:**
  - **Multidimensional eigenspaces,**
  - **Broken root chains;**

- ▶ **Main challenges for computing Chevalley bases in small characteristic:**
  - **Multidimensional eigenspaces,**
  - **Broken root chains;**
- ▶ **Found solutions for all cases, and implemented these:**
  - **MAGMA package, about 6000 lines,**
  - **soon to be available.**

- ▶ **Main challenges for computing Chevalley bases in small characteristic:**
  - **Multidimensional eigenspaces,**
  - **Broken root chains;**
- ▶ **Found solutions for all cases, and implemented these:**
  - **MAGMA package, about 6000 lines,**
  - **soon to be available.**
- ▶ **To do:**
  - **Compute split Cartan subalgebras in small characteristic;**

- ▶ **Main challenges for computing Chevalley bases in small characteristic:**
  - Multidimensional eigenspaces,
  - Broken root chains;
- ▶ **Found solutions for all cases, and implemented these:**
  - MAGMA package, about 6000 lines,
  - soon to be available.
- ▶ **To do:**
  - Compute split Cartan subalgebras in small characteristic;
- ▶ **Bigger picture:**
  - Recognition of groups or Lie algebras,
  - Finding conjugators for Lie group elements,
  - Finding automorphisms of Lie algebras,
  - ...

- ▶ What is a Lie algebra?
  - ▶ What is a Chevalley basis?
  - ▶ How to compute Chevalley bases?
  - ▶ What next?
- 
- ▶ **Questions?**