

# Construction of Chevalley Bases of Lie Algebras

Dan Roozmond

Joint work with Arjeh M. Cohen

December 3rd, 2008, EIDMA Combinatorial Seminar,  
Eindhoven University of Technology

<http://www.win.tue.nl/~droozemo/> (or Google)

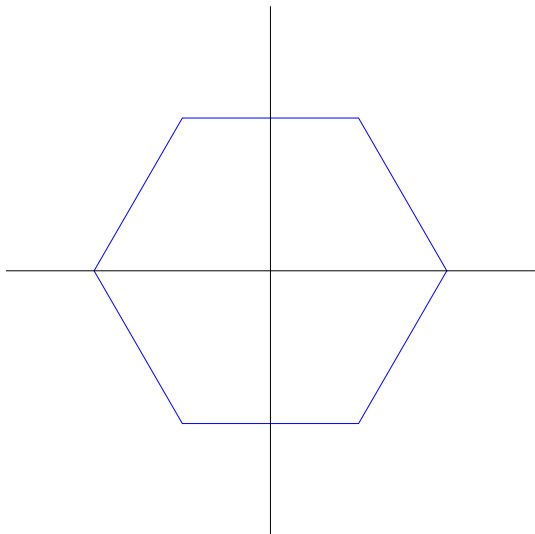
1. Why study Lie algebras?
2. Defining Lie algebras
  - Root system
  - Root datum
  - Lie algebra
3. Examples
  - $A_1, B_2, G_2$
  - $A_2$
4. Computing Chevalley Bases
  - Why?
  - How?
  - Strange things in small characteristic
  - Solving these things
5. Conclusion, Future research

- ▶ Study groups by Lie algebras:
  - Simple algebraic group  $G \leftrightarrow$  Unique Lie algebra  $L$
  - Many properties carry over to  $L$
  - Easier to calculate in  $L$
  - $G \leq \text{Aut}(L)$ , often even  $G = \text{Aut}(L)$
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  - Conjugation
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... and a thesis to be written ...

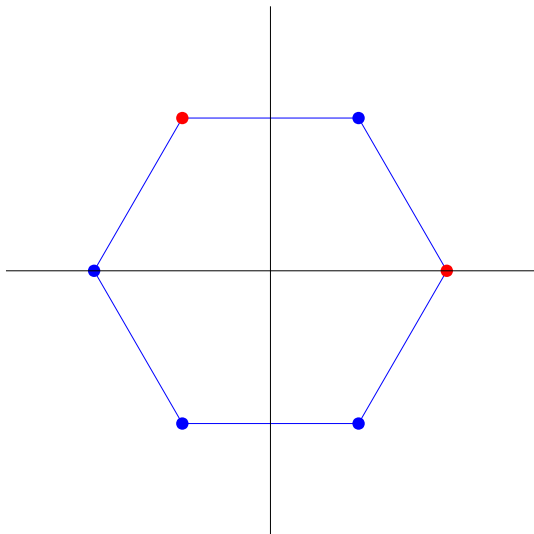
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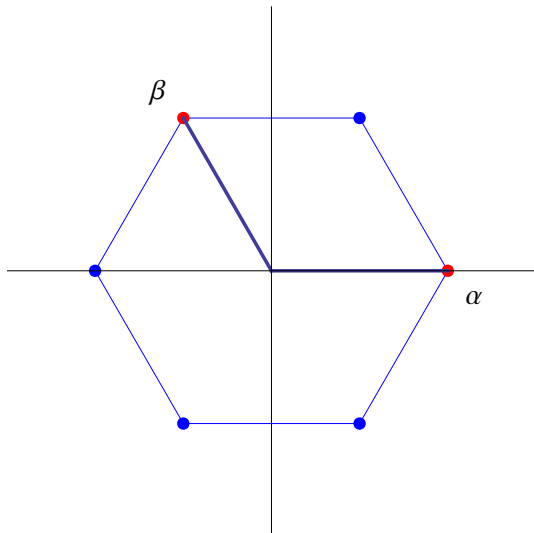


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- ▶ A root system of type  $A_2$
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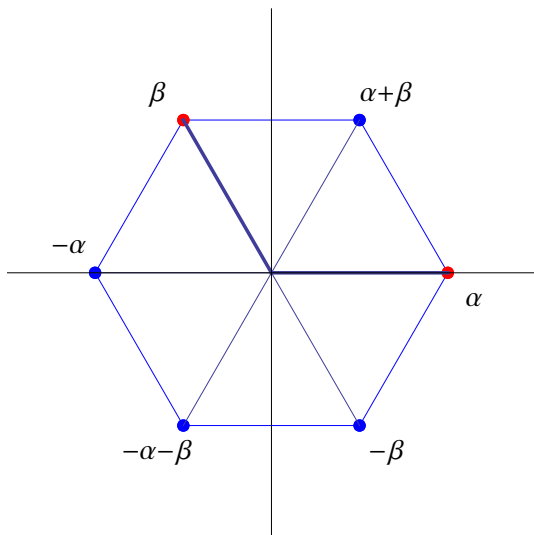


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## Definition (Root Datum)

$$R = (X, \Phi, Y, \Phi^\vee), \quad \langle \cdot, \cdot \rangle : X \times Y \rightarrow \mathbb{Z},$$

- ▶  $X, Y$ : dual free  $\mathbb{Z}$ -modules,
- ▶ put in duality by  $\langle \cdot, \cdot \rangle$ ,
- ▶  $\Phi \subseteq X$ : roots,
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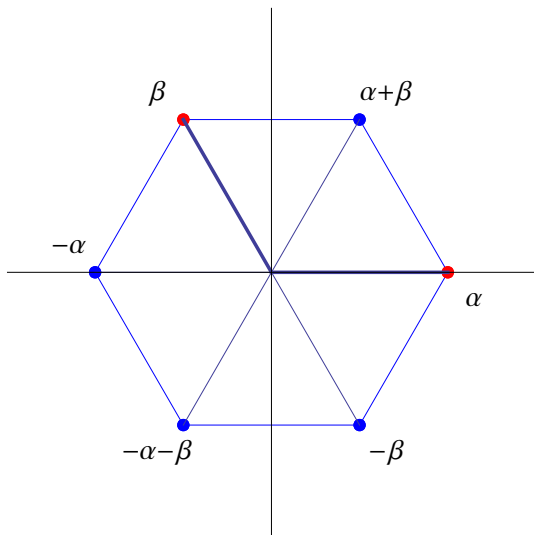
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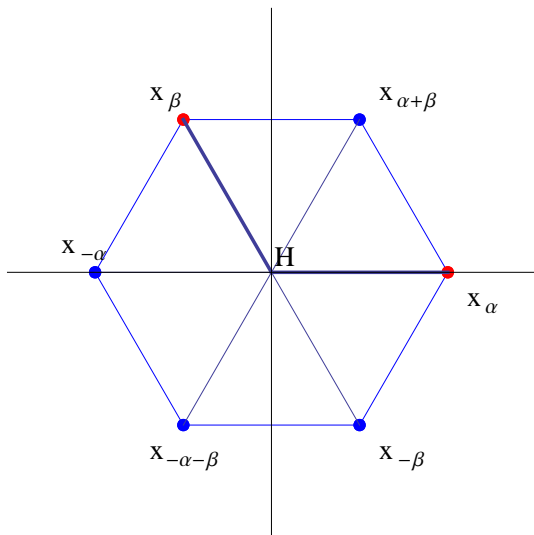
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$$\text{Formal basis : } L_{\mathbb{Z}} = \bigoplus_{i=1, \dots, n} \mathbb{Z}h_i \oplus \bigoplus_{\alpha \in \Phi} \mathbb{Z}x_{\alpha},$$

Multiplication :  $[\cdot, \cdot]$

with bilinear antisymmetric multiplication defined by

- ▶  $h_i, h_j \in H$  :  $[h_i, h_j] = 0,$
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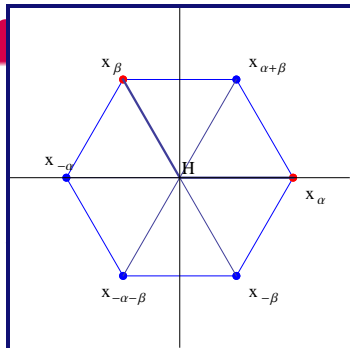
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$L_{\mathbb{F}} = L_{\mathbb{Z}} \otimes \mathbb{F}$  gives a Lie algebra over  $\mathbb{F}$ .

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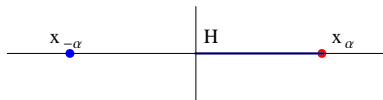
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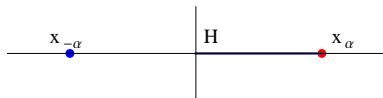
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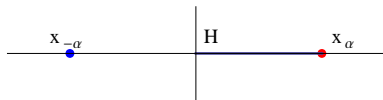
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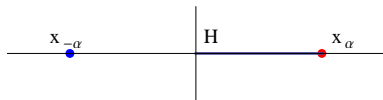
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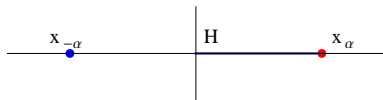
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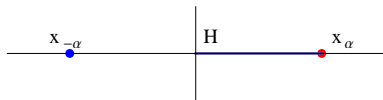
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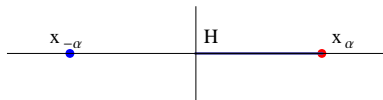
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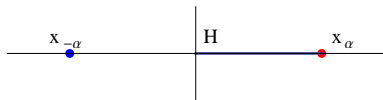
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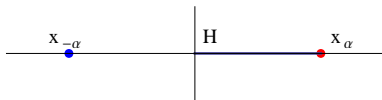
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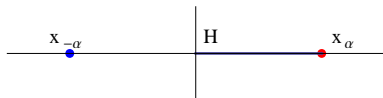
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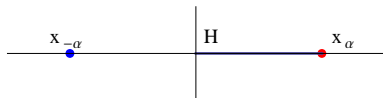
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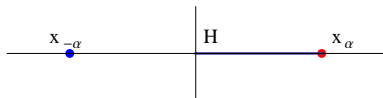
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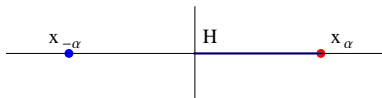
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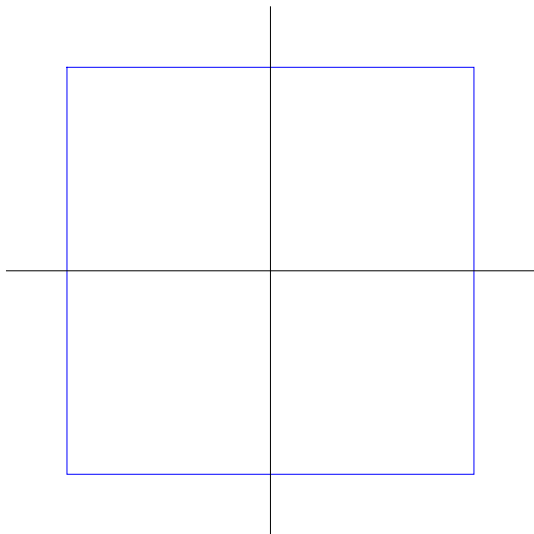
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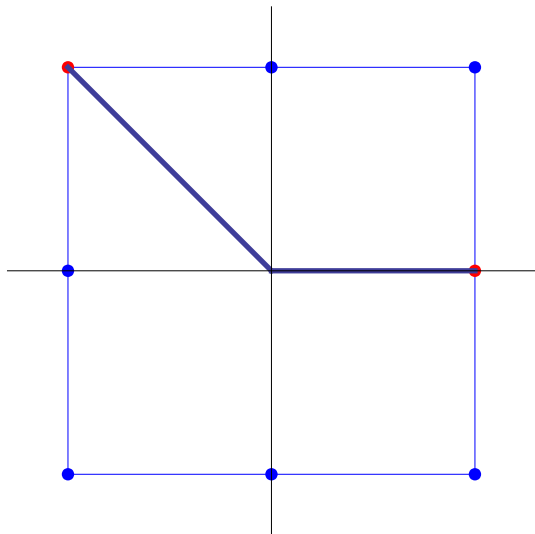
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$$\begin{aligned} L_{\mathbb{Z}} &= H \oplus \bigoplus_{\alpha \in \Phi} \mathbb{Z}x_\alpha \\ &= \mathbb{Z}h \oplus \mathbb{Z}x_\alpha \oplus \mathbb{Z}x_{-\alpha}, \end{aligned}$$

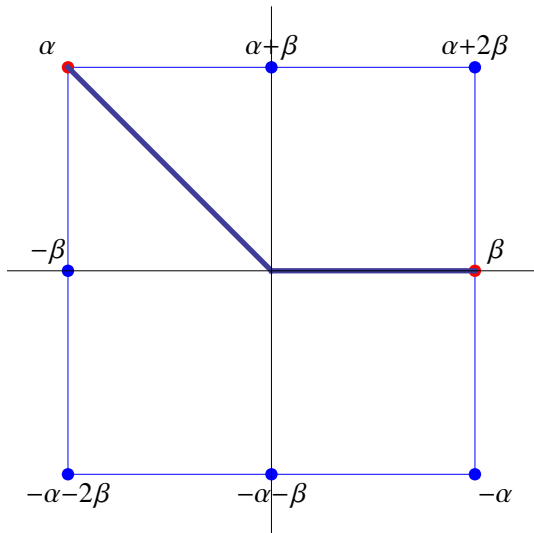
	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$-2h$	$x_\alpha$
$x_{-\alpha}$	$2h$	0	$-x_{-\alpha}$
$h$	$-x_\alpha$	$x_{-\alpha}$	0



- ▶ A square
- ▶ A root system of type  $B_2$
- ▶ A Lie algebra of type  $B_2$

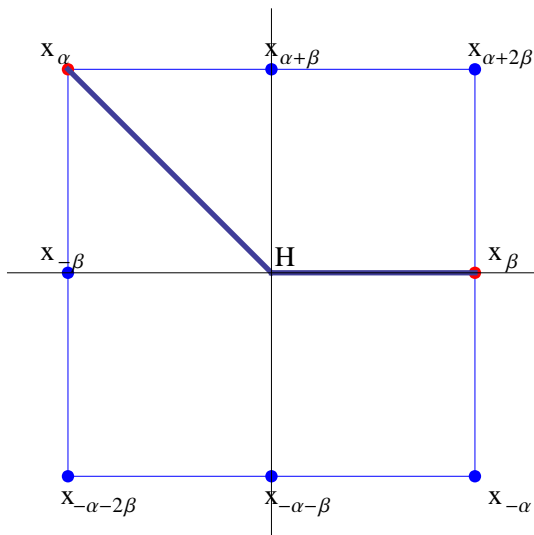


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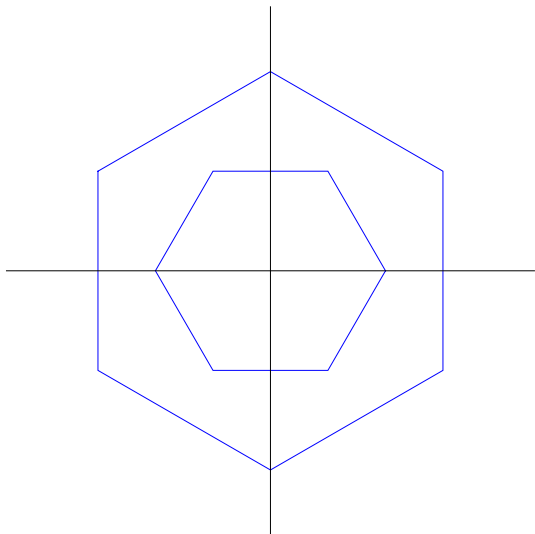


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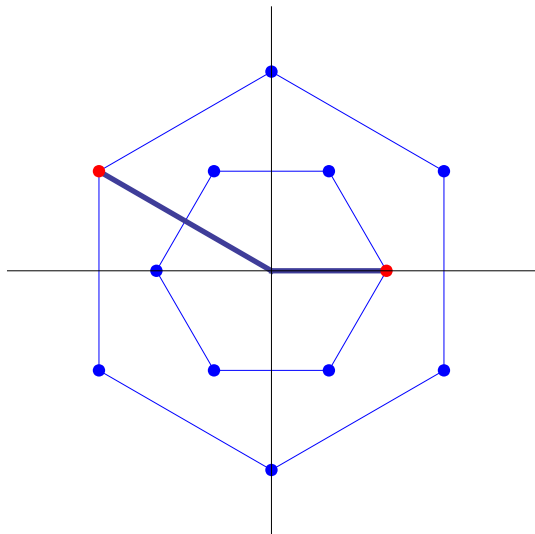




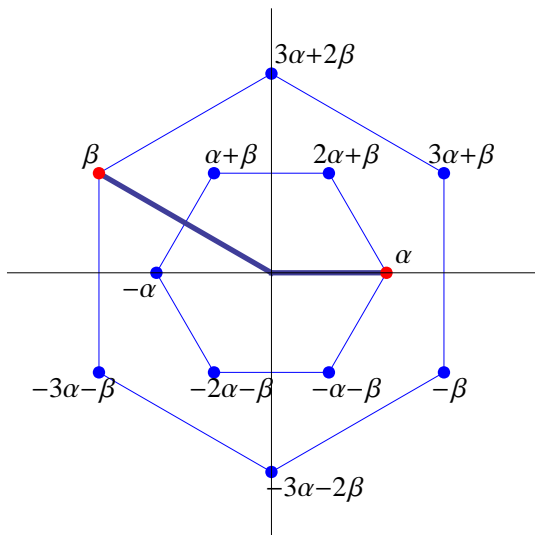
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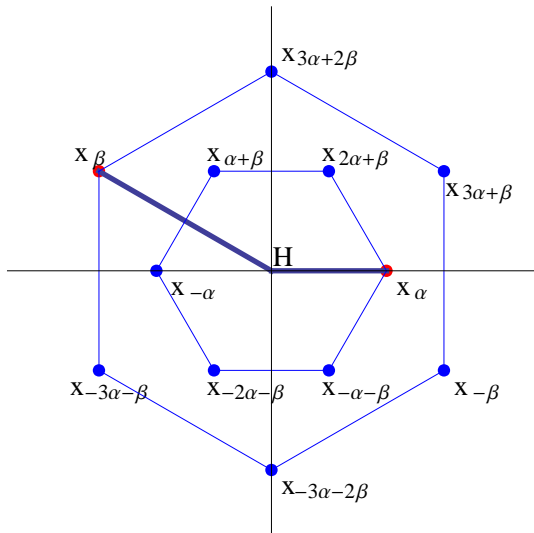
- ▶ **Two hexagons**
- ▶ A root system of type  $G_2$
- ▶ A Lie algebra of type  $G_2$



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1. Why study Lie algebras?
2. Defining Lie algebras
  - Root system
  - Root datum
  - Lie algebra
3. Examples
  - $A_1, B_2, G_2$
  - $A_2$
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  - Why?
  - How?
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- ▶  $L =$  matrices,  $3 \times 3$ , trace 0;
- ▶  $[x, y] := xy - yx$ ;
- ▶

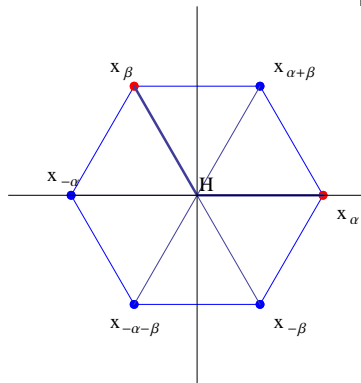
$$H = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix};$$

- ▶ Claim:  $L$  is of type  $A_2$ .

- ▶  $h_i, h_j \in H$  :  $[h_i, h_j] = 0,$
- ▶  $h_i \in H, \alpha \in \Phi$  :  $[x_\alpha, h_i] = \langle \alpha, f_i \rangle x_\alpha,$
- ▶  $\alpha \in \Phi$  :  $[x_{-\alpha}, x_\alpha] = \sum_{i=1}^n \langle e_i, \alpha^\vee \rangle h_i,$
- ▶  $\alpha, \beta \in \Phi$  :  $[x_\alpha, x_\beta] = \begin{cases} N_{\alpha, \beta} x_{\alpha+\beta} & \text{if } \alpha + \beta \in \Phi, \\ 0 & \text{otherwise.} \end{cases}$

“Adjoint” root datum:

- ▶ Pos. roots:  $(1, 0), (0, 1), (1, 1),$
- ▶ Pos. coroots:  $(2, -1), (-1, 2), (1, 1).$

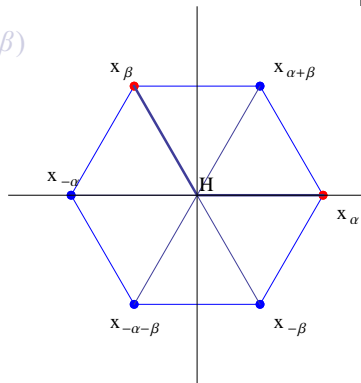




- ▶ So we can compute a Chevalley basis Chevalley bases in this case!
- ▶ And thus exhibit a (quite special) element of  $\text{Aut}(L)$ :

$$\begin{aligned} \alpha &\leftrightarrow -\alpha \\ \beta &\leftrightarrow \alpha + \beta \\ -\beta &\leftrightarrow -(\alpha + \beta) \end{aligned}$$

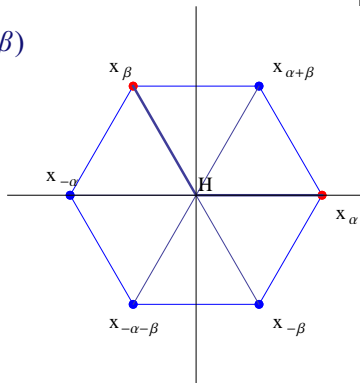
- ▶ Can we make the machine do this?



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- ▶ Can we make the machine do this?



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## Definition (Chevalley Lie Algebra)

$$\text{Formal basis : } L_{\mathbb{Z}} = \bigoplus_{i=1, \dots, n} \mathbb{Z}h_i \oplus \bigoplus_{\alpha \in \Phi} \mathbb{Z}x_{\alpha},$$

Multiplication :  $[\cdot, \cdot]$

$L_{\mathbb{F}} = L_{\mathbb{Z}} \otimes \mathbb{F}$  gives a Lie algebra over  $\mathbb{F}$ .

- ▶ Idea: Given **any** Lie algebra, find a Chevalley basis.
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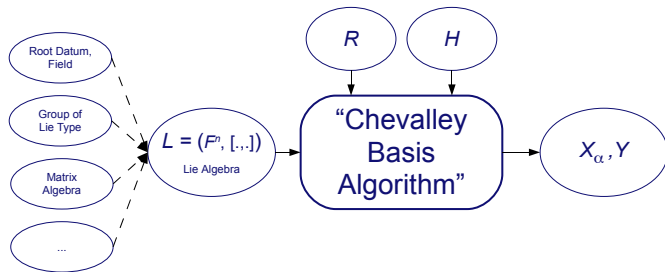
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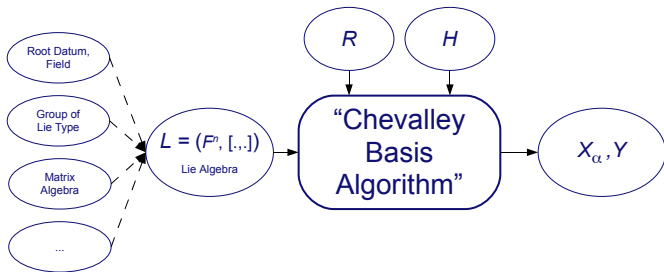


(Cohen/Murray, indep. Ryba)

Also given: Root datum  $R$ , splitting Cartan subalgebra  $H = Y \otimes \mathbb{F}$   
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Char. 0,  $p \geq 5$ : Implemented in GAP, Magma



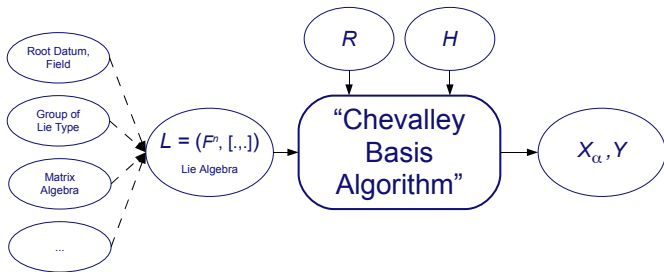


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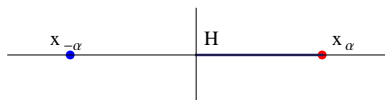
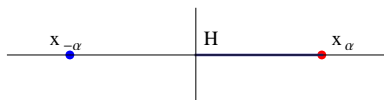
## CHEVALLEYBASIS

**in:** A simple Lie algebra  $L$ ,  
a splitting Cartan subalgebra  $H$  of  $L$ , and  
a root datum  $R = (X, \Phi, Y, \Phi^\vee)$ .  
**out:** A Chevalley basis  $B$  for  $L$  with respect to  $H$  and  $R$ .  
**begin**

- 1 **let**  $\{E_1, \dots, E_m\} = \text{DIAGONALIZE}(L, H)$ ,
- 2 **let**  $\{\bar{X}_1, \dots, \bar{X}_{|\Phi|}\} = \text{STRAIGHTEN}(L, \{E_1, \dots, E_m\})$ ,
- 3 **let**  $\iota = \text{IDENTIFYROOTS}(L, R, \{\bar{X}_1, \dots, \bar{X}_{|\Phi|}\})$ ,
- 4 **let**  $[X_\alpha \mid \alpha \in \Phi], [h_1, \dots, h_{\text{rnk}(\Phi)}] = \text{SCALETOBASIS}(L, H, \{\bar{X}_1, \dots, \bar{X}_{|\Phi|}\}, \iota)$ ,
- 5 **return**  $[X_\alpha \mid \alpha \in \Phi], [h_1, \dots, h_{\text{rnk}(\Phi)}]$ .

**end**

**Algorithm:** Finding a Chevalley Basis

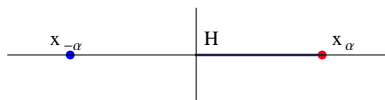
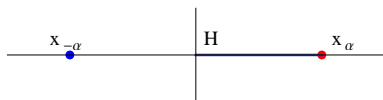


	$x_\alpha$	$x_{-\alpha}$	$h$
$x_\alpha$	0	$-h$	$2x_\alpha$
$x_{-\alpha}$	$h$	0	$-2x_{-\alpha}$
$h$	$-2x_\alpha$	$2x_{-\alpha}$	0

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Observe:

- ▶  $h \mapsto \frac{1}{2}h$  maps  $\text{Lie}(A_1^{\text{sc}}, \mathbb{F})$  to  $\text{Lie}(A_1^{\text{ad}}, \mathbb{F})$ ,
- ▶ So  $\text{Lie}(A_1^{\text{sc}}, \mathbb{F}) \cong \text{Lie}(A_1^{\text{ad}}, \mathbb{F})$ ,
- ▶ Except if  $\text{char}(\mathbb{F}) = 2!$

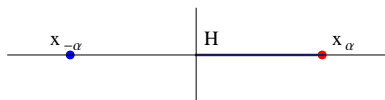
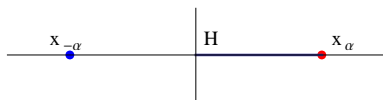


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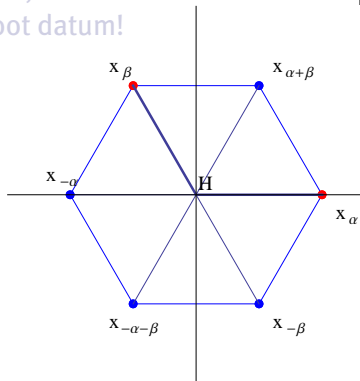
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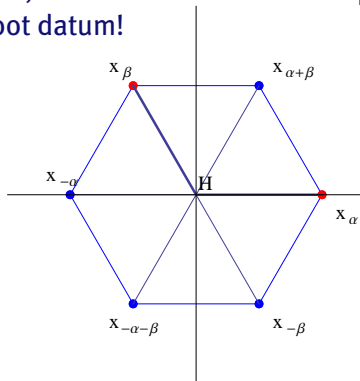
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- ▶  $h_1 = -\frac{2}{3}c_1 - \frac{1}{3}c_2$   
 $h_2 = -\frac{1}{3}c_1 - \frac{2}{3}c_2$
- ▶ But then what happens in char. 3 ?!
- ▶ We computed with the “adjoint” root datum; but  
Trace 0 matrices  $\leftrightarrow$  “simply connected” root datum!
- ▶ Isomorphic  $\leftrightarrow$  char.  $\neq 3$ !

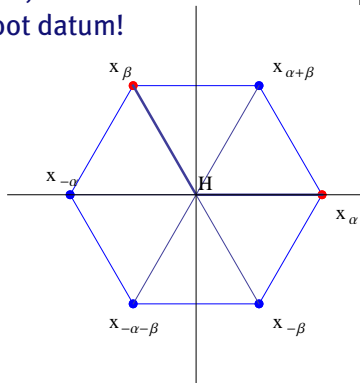


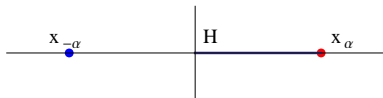
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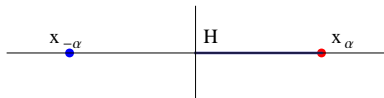


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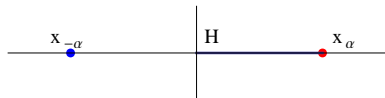
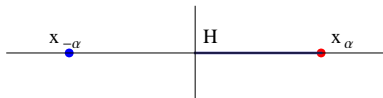


	$x_\alpha$	$x_{-\alpha}$	$h$	$\mathbb{Z}^1$
$x_\alpha$	0	$-h$	$2x_\alpha$	(2)
$x_{-\alpha}$	$h$	0	$-2x_{-\alpha}$	(-2)
$h$	$-2x_\alpha$	$2x_{-\alpha}$	0	(0)



	$x_\alpha$	$x_{-\alpha}$	$h$	$\mathbb{Z}^1$
$x_\alpha$	0	$-2h$	$x_\alpha$	(1)
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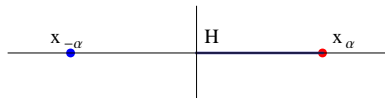
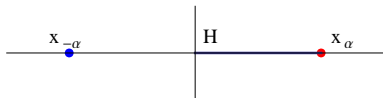
- ▶ Use action of  $H$  to diagonalize  $L$  and find  $x_\alpha$ ,
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	...	$h_1$	$h_2$	$\mathbb{Z}$
$x_\alpha$		$2x_\alpha$	$-x_\alpha$	$(2, -1)$
$x_\beta$		$-3x_\beta$	$2x_\beta$	$(-3, 2)$
$x_{\alpha+\beta}$		$-x_{\alpha+\beta}$	$x_{\alpha+\beta}$	$(-1, 1)$
$x_{2\alpha+\beta}$		$x_{2\alpha+\beta}$	$0$	$(1, 0)$
$x_{3\alpha+\beta}$		$3x_{3\alpha+\beta}$	$-x_{3\alpha+\beta}$	$(3, -1)$
$x_{3\alpha+2\beta}$		$0$	$x_{3\alpha+2\beta}$	$(0, 1)$
$\vdots$				

	...	$h_1$	$h_2$	$\mathbb{Z}$
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$x_{3\alpha+\beta}$		$3x_{3\alpha+\beta}$	$-x_{3\alpha+\beta}$	$(3, -1)$
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$x_{3\alpha+2\beta}$		$0$	$x_{3\alpha+2\beta}$	$(0, 1)$
$x_{-\alpha}$		$-2x_{-\alpha}$	$x_{-\alpha}$	$(-2, 1)$
$x_{-\beta}$		$3x_{-\beta}$	$-2x_{-\beta}$	$(3, -2)$
$x_{-\alpha-\beta}$		$x_{-\alpha-\beta}$	$-x_{-\alpha-\beta}$	$(1, -1)$
$x_{-2\alpha-\beta}$		$-x_{-2\alpha-\beta}$	$0$	$(-1, 0)$
$x_{-3\alpha-\beta}$		$-3x_{-3\alpha-\beta}$	$x_{-3\alpha-\beta}$	$(-3, 1)$
$x_{-3\alpha-2\beta}$		$0$	$-x_{-3\alpha-2\beta}$	$(0, -1)$
$\vdots$				

	...	$h_1$	$h_2$	$\mathbb{Z}$	$\text{GF}(3^m)$
$x_\alpha$		$2x_\alpha$	$-x_\alpha$	$(2, -1)$	$(-1, -1)$
$x_\beta$		$-3x_\beta$	$2x_\beta$	$(-3, 2)$	$(0, -1)$ (!)
$x_{\alpha+\beta}$		$-x_{\alpha+\beta}$	$x_{\alpha+\beta}$	$(-1, 1)$	$(-1, 1)$
$x_{2\alpha+\beta}$		$x_{2\alpha+\beta}$	$0$	$(1, 0)$	$(1, 0)$
$x_{3\alpha+\beta}$		$3x_{3\alpha+\beta}$	$-x_{3\alpha+\beta}$	$(3, -1)$	$(0, -1)$ (!)
$x_{3\alpha+2\beta}$		$0$	$x_{3\alpha+2\beta}$	$(0, 1)$	$(0, 1)$
$x_{-\alpha}$		$-2x_{-\alpha}$	$x_{-\alpha}$	$(-2, 1)$	$(1, 1)$
$x_{-\beta}$		$3x_{-\beta}$	$-2x_{-\beta}$	$(3, -2)$	$(0, 1)$
$x_{-\alpha-\beta}$		$x_{-\alpha-\beta}$	$-x_{-\alpha-\beta}$	$(1, -1)$	$(1, -1)$
$x_{-2\alpha-\beta}$		$-x_{-2\alpha-\beta}$	$0$	$(-1, 0)$	$(-1, 0)$
$x_{-3\alpha-\beta}$		$-3x_{-3\alpha-\beta}$	$x_{-3\alpha-\beta}$	$(-3, 1)$	$(0, 1)$
$x_{-3\alpha-2\beta}$		$0$	$-x_{-3\alpha-2\beta}$	$(0, -1)$	$(0, -1)$ (!)
$\vdots$					



	...	$h_1$	$h_2$	$\mathbb{Z}$	$\text{GF}(3^m)$
$x_\alpha$		$2x_\alpha$	$-x_\alpha$	$(2, -1)$	$(-1, -1)$
$x_\beta$		$-3x_\beta$	$2x_\beta$	$(-3, 2)$	$(0, -1)$ (!)
$x_{\alpha+\beta}$		$-x_{\alpha+\beta}$	$x_{\alpha+\beta}$	$(-1, 1)$	$(-1, 1)$
$x_{2\alpha+\beta}$		$x_{2\alpha+\beta}$	$0$	$(1, 0)$	$(1, 0)$
$x_{3\alpha+\beta}$		$3x_{3\alpha+\beta}$	$-x_{3\alpha+\beta}$	$(3, -1)$	$(0, -1)$ (!)
$x_{3\alpha+2\beta}$		$0$	$x_{3\alpha+2\beta}$	$(0, 1)$	$(0, 1)$ (! <sup>2</sup> )
$x_{-\alpha}$		$-2x_{-\alpha}$	$x_{-\alpha}$	$(-2, 1)$	$(1, 1)$
$x_{-\beta}$		$3x_{-\beta}$	$-2x_{-\beta}$	$(3, -2)$	$(0, 1)$ (! <sup>2</sup> )
$x_{-\alpha-\beta}$		$x_{-\alpha-\beta}$	$-x_{-\alpha-\beta}$	$(1, -1)$	$(1, -1)$
$x_{-2\alpha-\beta}$		$-x_{-2\alpha-\beta}$	$0$	$(-1, 0)$	$(-1, 0)$
$x_{-3\alpha-\beta}$		$-3x_{-3\alpha-\beta}$	$x_{-3\alpha-\beta}$	$(-3, 1)$	$(0, 1)$ (! <sup>2</sup> )
$x_{-3\alpha-2\beta}$		$0$	$-x_{-3\alpha-2\beta}$	$(0, -1)$	$(0, -1)$ (!)
$\vdots$					

## Steinberg, 1961

Complete list of multiplicities of roots, for root data of adjoint type

## Cohen, R., 2008

Complete list of multiplicities of roots, for all root data

Char.	Root datum	Eigenspace dims
3	$A_2^{sc}$	$3^2$
3	$G_2$	$1^6, 3^2$
2	$A_3^{sc}, A_3^{(a)*}$	$4^3$
2	$B_n^{ad} (n \geq 2)$	$2^n, 4^{\binom{n}{2}}$
2	$B_2^{sc}$	$4^2$
2	$B_3^{sc}$	$6^3$
2	$B_4^{sc}$	$2^4, 8^3$
2	$B_n^{sc} (n \geq 5)$	$2^n, 4^{\binom{n}{2}}$
2	$C_n^{ad} (n \geq 3)$	$2n^1, 2^{2\binom{n}{2}}$
2	$C_n^{sc} (n \geq 3)$	$2n^1, 4^{\binom{n}{2}}$
2	$D_4^{(a),(b),(a+b)*}$	$4^6$
2	$D_4^{sc}$	$8^3$
2	$D_n^{(a)*}, D_n^{sc} (n \geq 5)$	$4^{\binom{n}{2}}$
2	$F_4$	$2^{12}, 8^3$
2	$G_2$	$4^3$
2	all remaining cases	$2^N (N =  \Phi^+ )$

## Steinberg, 1961

Complete list of multiplicities of roots, for root data of adjoint type

## Cohen, R., 2008

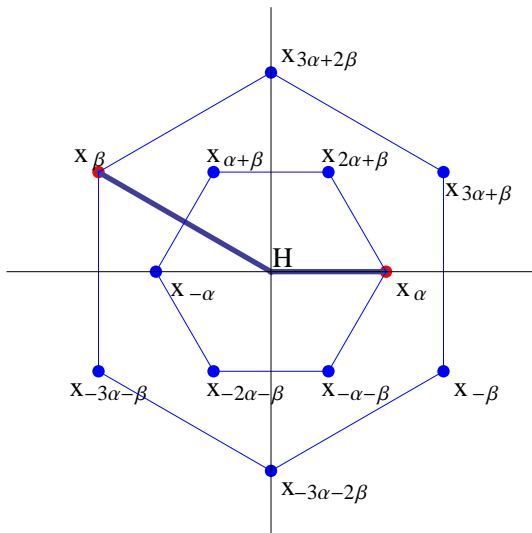
Complete list of multiplicities of roots, for all root data

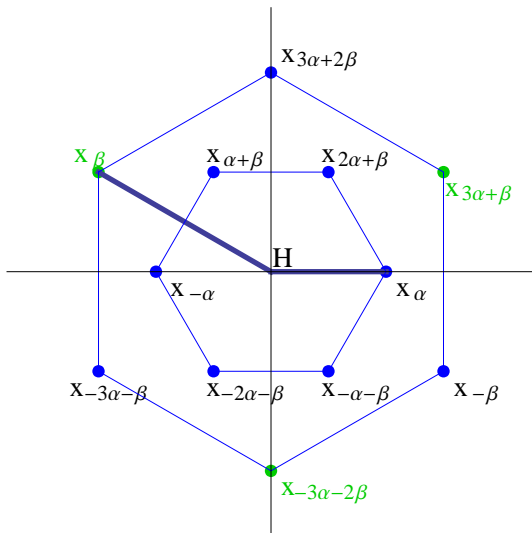
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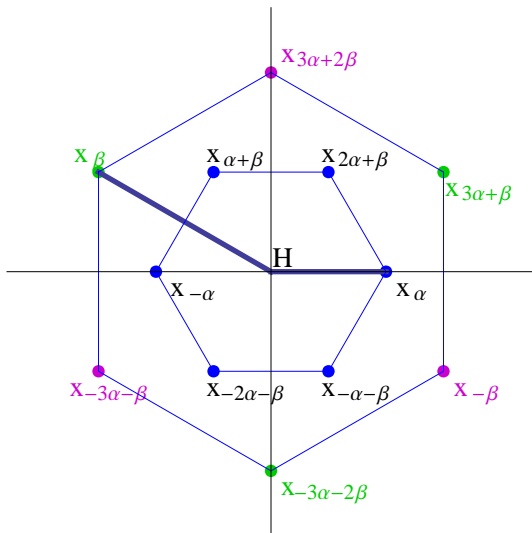
1. Why study Lie algebras?
2. Defining Lie algebras
  - Root system
  - Root datum
  - Lie algebra
3. Examples
  - $A_1, B_2, G_2$
  - $A_2$
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  - How?
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5. Conclusion, Future research

## General Solution Strategies:

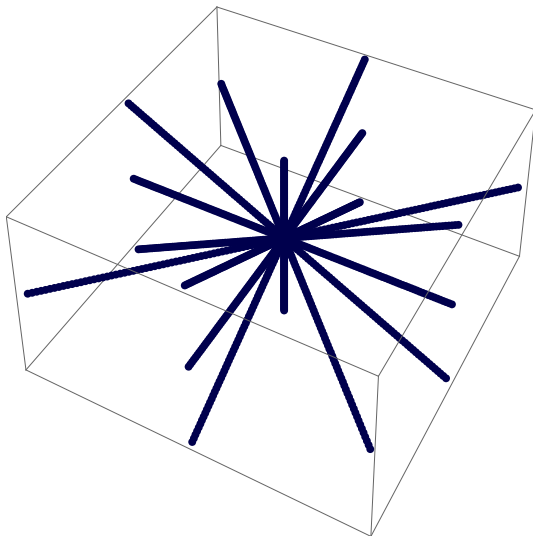
1. Nullspaces (ex:  $G_2$ , char. 3),
2. Ideals (ex:  $B_3$ , char. 2),
3. Derivation Algebra (ex:  $A_2$ , char. 3)

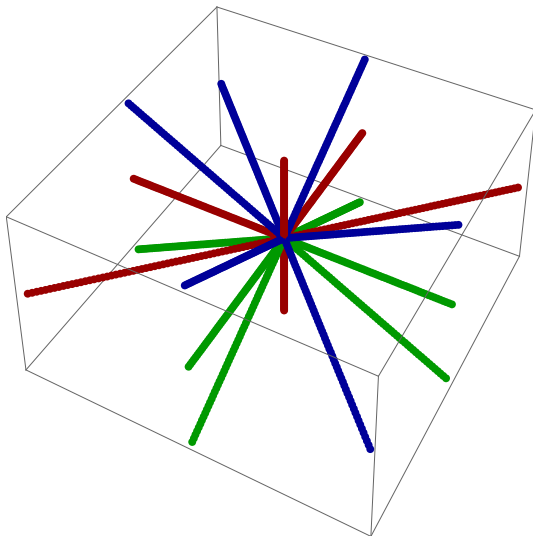


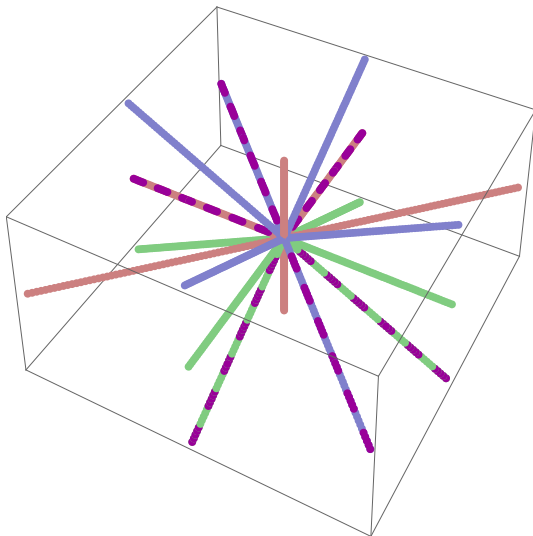












$L$  a Lie algebra,

## Definition (Derivation Algebra)

$$\text{Der}(L) = \{D \in \text{End}(L) \mid D[x, y] = [Dx, y] + [x, Dy]\}.$$

Observations:

- ▶  $\text{Der}(L)$  with  $[D, E] = DE - ED$  is a Lie algebra:
- ▶  $L \subseteq \text{Der}(L)$  via  $\text{ad}$ :

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$$\begin{aligned} [D, [E, F]](x) &= D(EFx) = D([E, F(x)]) \\ &= [DE, F(x)] + [E, DF(x)] \\ &= [[D, E], F](x) + [E, [D, F]](x) \\ &= (-[E, [F, D]] - [F, [D, E]])(x) \end{aligned}$$

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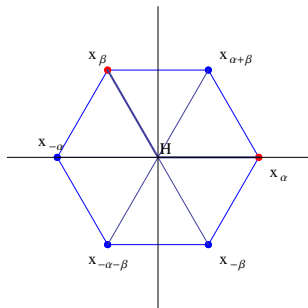
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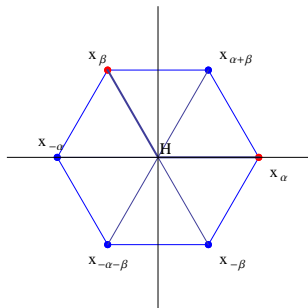
$$\text{ad}_t([x, y]) = [t, [x, y]] = [x, [t, y]] + [[t, x], y]$$



Type	Eigenspaces	Composition
Ad:	$0^2, 1^6$	$\frac{1}{7}$
SC:	$0^2, 3^2$	$\frac{7}{1}$

Observations:

- ▶ There is only one “7”,
- ▶  $\text{Der}(L^{\text{SC}}) = L^{\text{ad}}$ .



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- ▶ Main challenges for computing Chevalley bases in small characteristic:
  - Multidimensional eigenspaces,
  - Broken root chains,
- ▶ Found solutions for majority of the cases,
  - And implemented these in MAGMA,
- ▶ Bigger picture:
  - Recognition of groups or Lie algebras,
  - Finding conjugators for Lie group elements,
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  - ...

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